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# Impedance-Based Stability Assessment of Power Systems: Correlation Study on Operating Conditions, Mode frequencies, and Stability Margins

Paper-ID: EA-025

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# 1. Background and Objective

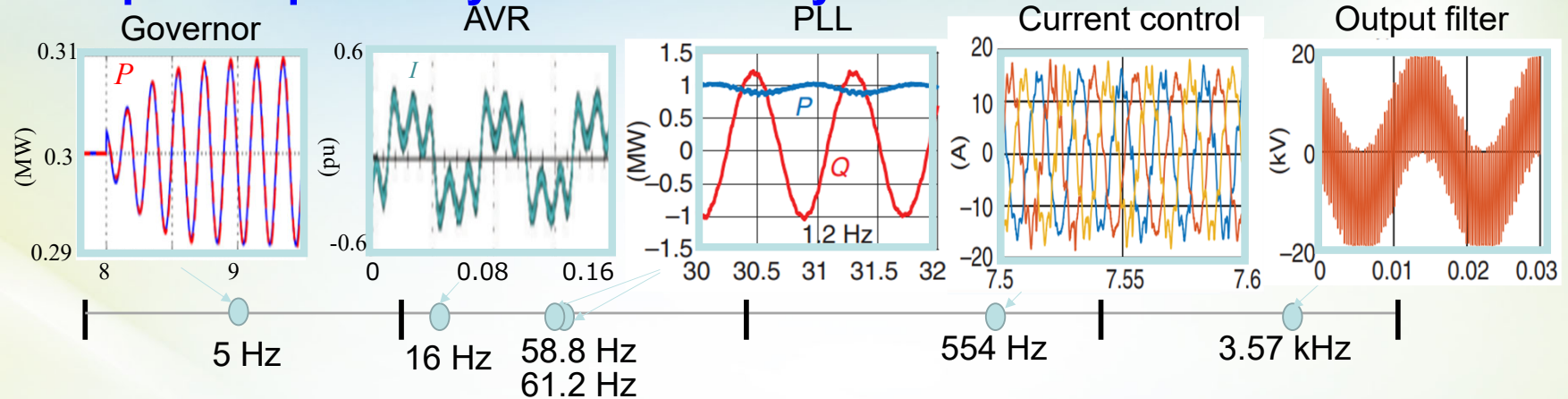
2. Case Studies and Results

3. Conclusion





## Examples of power system instability



[Ref.]

NREL: 10.1109/MELE.2020.3047166, S. Chen: 10.1109/TPEL.2025.3557035, J. Wang: 10.35833/MPCE.2024.000903

Above oscillations are caused by IBRs (inverter-based power resources).

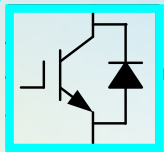
**Preliminary stability analysis is crucial.**

→ **Impedance based analysis** has gained significant attention.

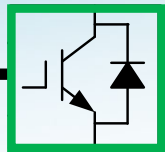


# Features of impedance-based analysis

Source

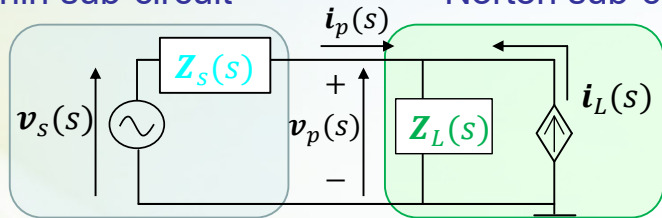


Thevenin sub-circuit



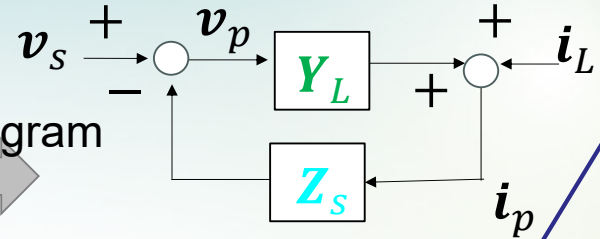
Norton sub-circuit

Load

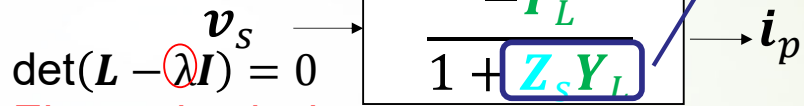


system divided into two subsystems

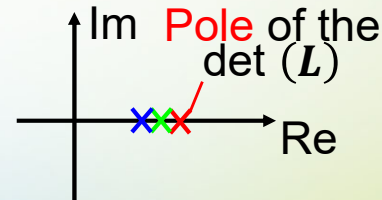
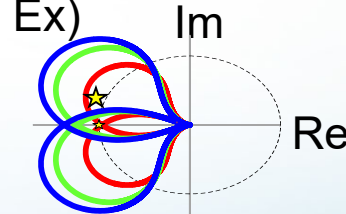
Block diagram



Loop Gain  $L = Z_S Z_L^{-1}$



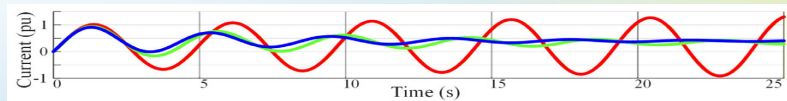
$\det(L - \lambda I) = 0$   
Eigenvalue loci



## The Generalized Nyquist Criterion (GNC)

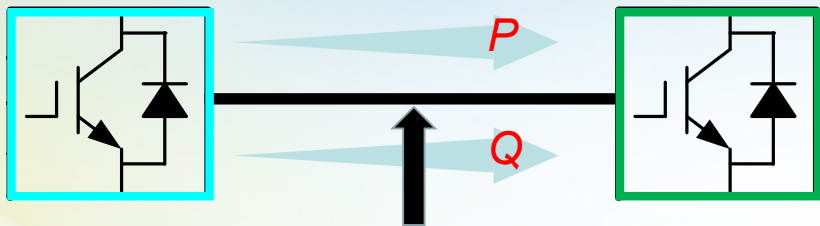
- Loop gain :  $L = Z_S Z_L^{-1}$
- Characteristic equation :  $\det(L - \lambda I) = 0$

Stability is determined by  $Z_S$  and  $Z_L$ .





# Relation of $Z$ , $\lambda$ and Stability

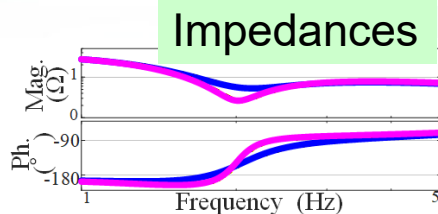
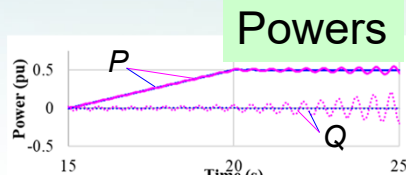


**Stable? Unstable?**

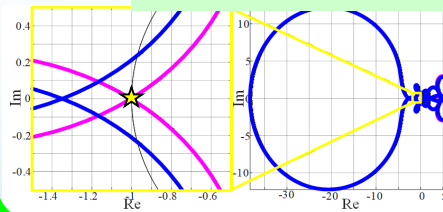
Ex)

Operating Point	IBR Parameter	Ex) PLL Proportional Gain
$(P,Q) = (0.5,0)$	6	12
$(P,Q) = (0.8,-0.8)$	Unstable	Unstable

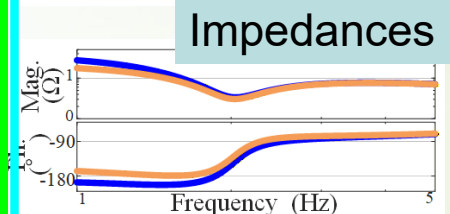
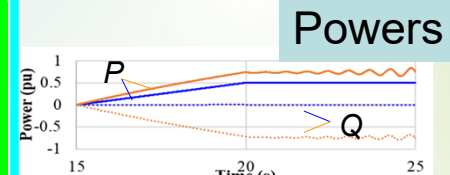
## IBR Parameter Change



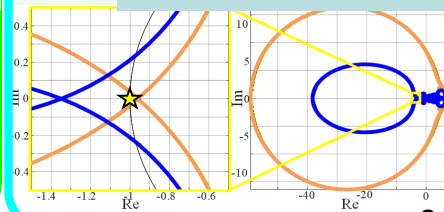
### $\lambda$ & Stabilities



## Operating Point Change



### $\lambda$ & Stabilities







## To be solved problem

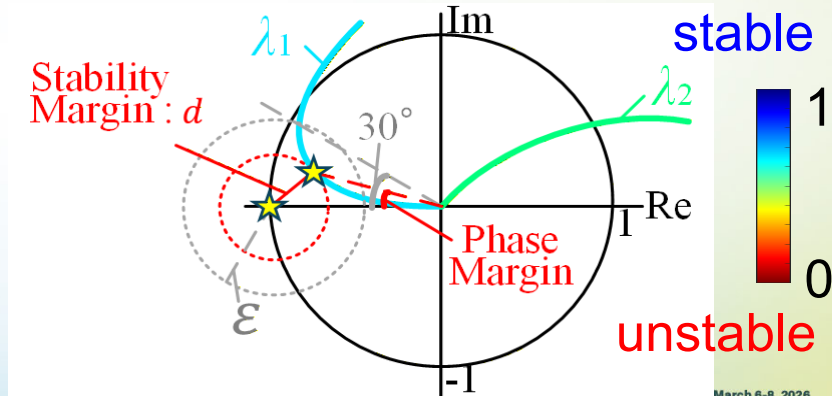
- Avoiding the unstable operation without stopping IBRs.
- Assessing the power system stability without using the GNC

## Aim of the Research

Analysis and Improving the Grid Stability **By Changing the Power Flows**  
**Without Stopping the Inverter-Operation**

## Stability Margin : $d$

- Evaluate the **minimum distance** between the **eigenvalue loci** and the **critical point**  $(-1,0)$ .
- The distance is evaluated under the **phase-margin of  $30^\circ$** .





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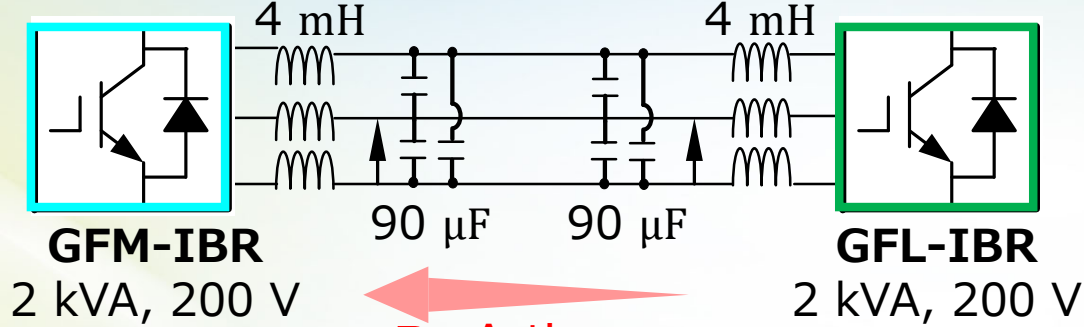






## Case Studies

### Test System Configuration

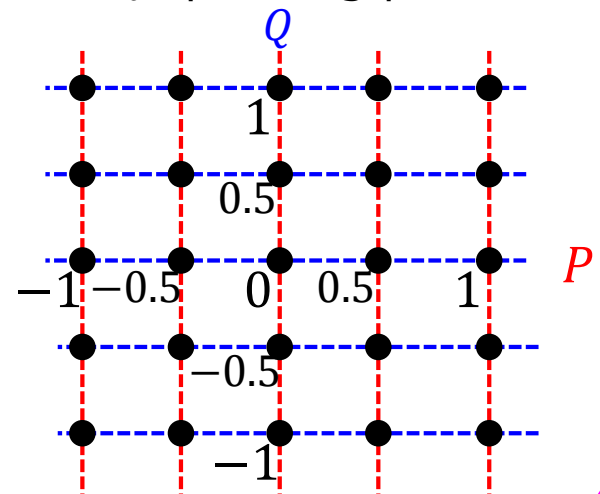


$P$  Active-power

$Q$  Lagging reactive power

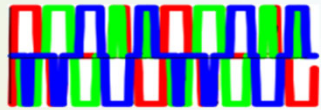
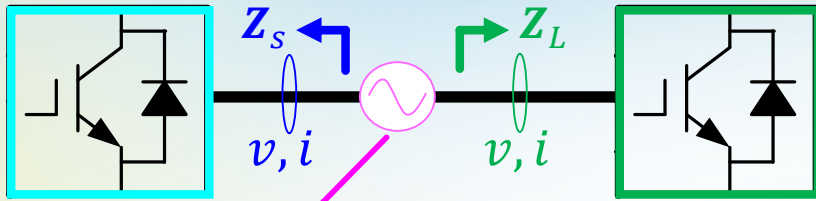
### Test Cases

$P$ - $Q$  operating points





## Measured Impedance

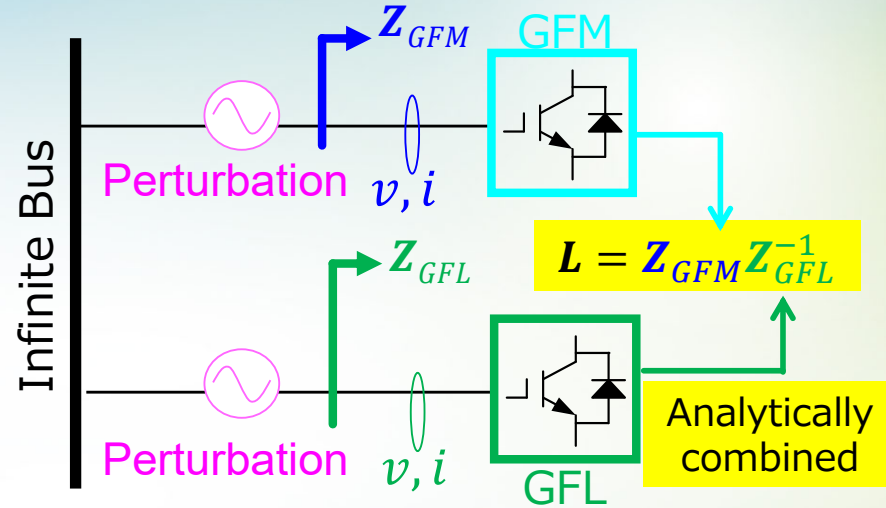


Perturbation  
(5% of system)



Perturbation generator

Perturbations worsen the resonance,  
and safe measurement becomes difficult.

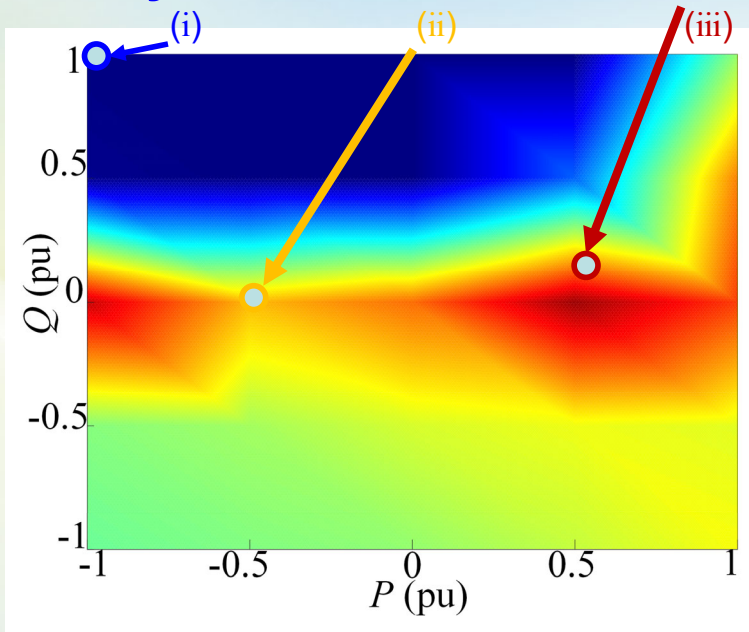


- Each impedance can be measured in safe.
- Stability was evaluated by combining both impedances analytically.

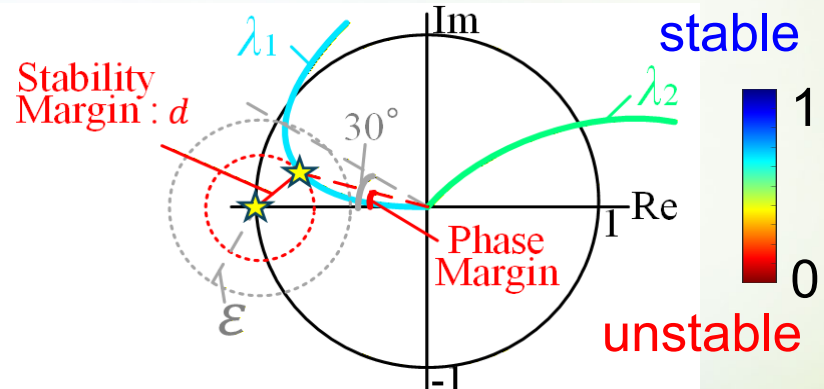
[Ref.] T. Ide (10.1109/ECCE-Europe62795.2025.11238886)



## Stability Assessment



- Loop gain :  $L = Z_s Z_L^{-1}$       Eigenvalue loci
- Characteristic equation :  $\det(L + \lambda I) = 0$
- Stability margin  $d$  :  $d = \min|\lambda - (-1, 0)|$

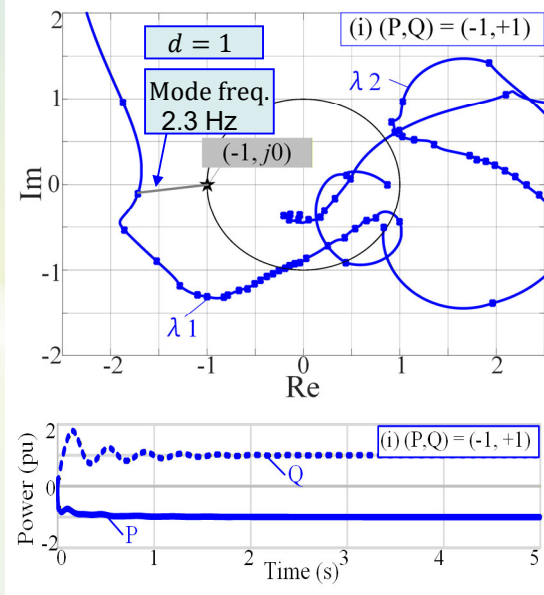


[Ref.] M. Amin (10.1002/047134608x.w1026.pub2)

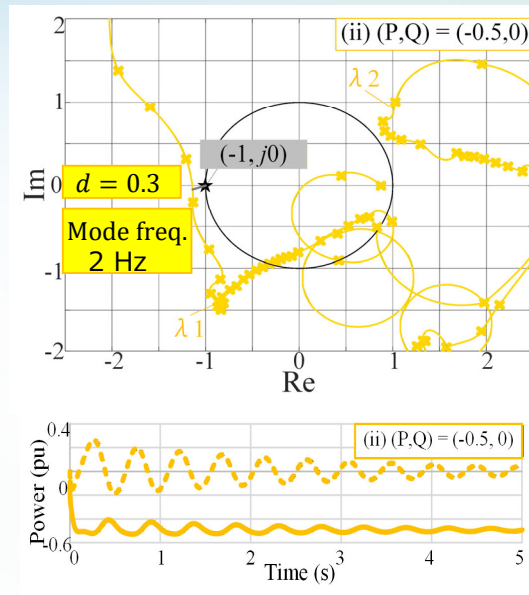
Only the second quadrant ( $-P, +Q$ ) is stable, all other operating conditions are unstable.



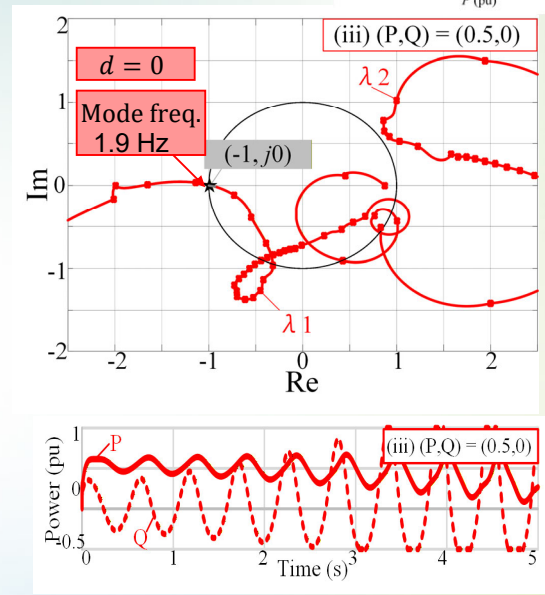
# Stability Assessment



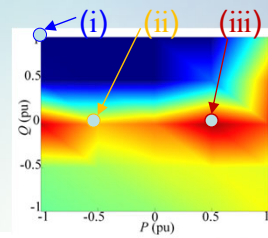
(i)



(ii)



(iii)



The map was validated using time- and frequency-domain responses.



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## Proposed Method

**Objective** : Avoid unstable conditions without stopping the inverter.

**Approach** : Evaluate stability at each power flow operating point.

## Key Achievements

- ✓ Mapping stability metrics over a wide range of power-flow conditions enables a rigorous and intuitive stability assessment.
- ✓ This map enables the prediction of potentially unstable power flows in advance, allowing countermeasures such as adjusting generation output or temporarily suppressing IBR.  
→ Consequently, it avoids the need for inverter shutdowns or redesigns.







# Thank you for your kind attention !

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