

This study was based on the results obtained from a project commissioned by the New Energy and Industrial Technology Development Organization (NEDO), no. JPNP19002.

Performance Evaluation of Grid-Following and Grid-Forming Inverters with Virtual Inertia Controls

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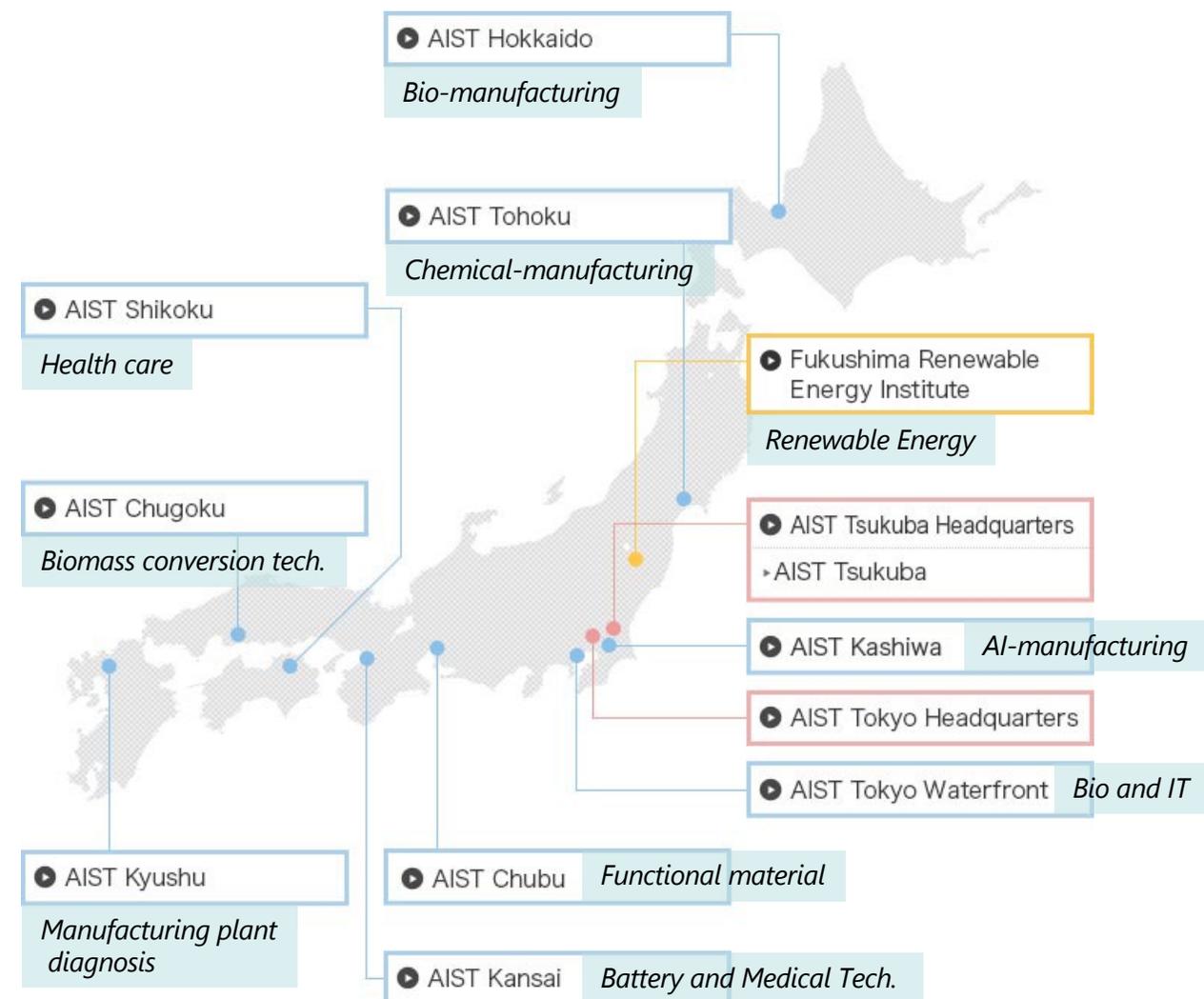
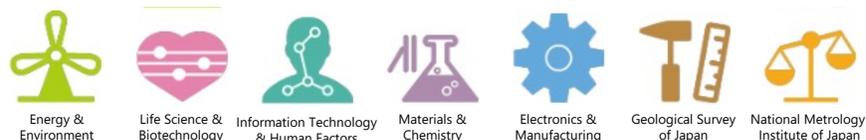
- Why virtual inertia control of IBR?

- Performance evaluation of GFL and GFM inverters
 - PHIL testing using IEEE 9-bus system model
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- Summary

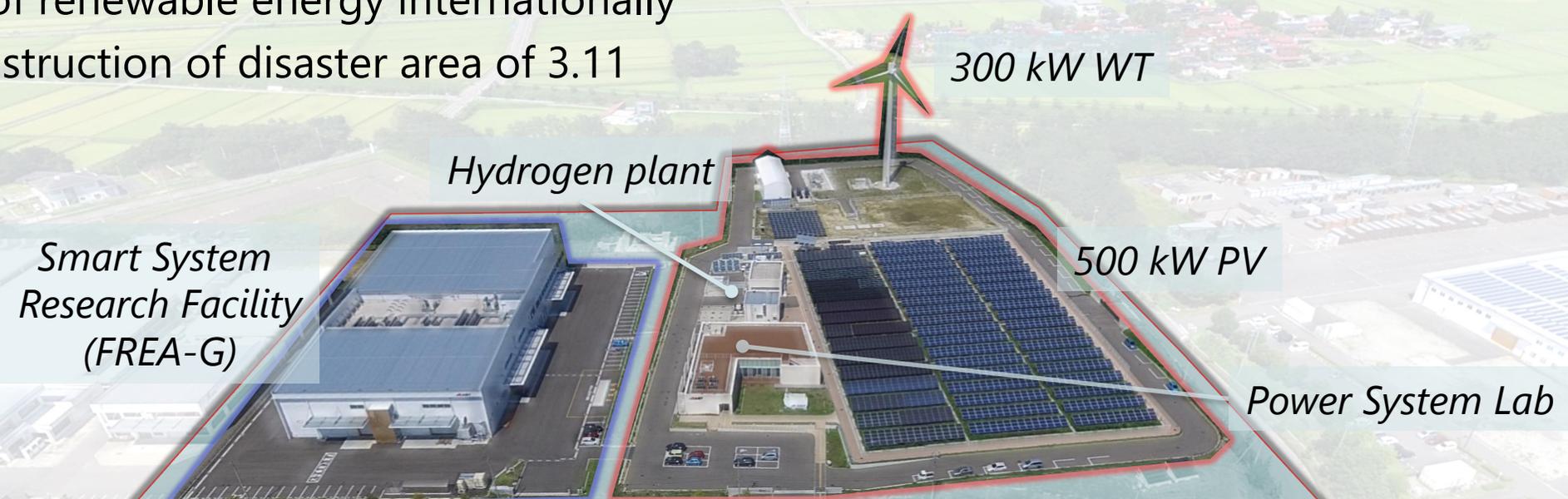
AIST (National Institute of **A**dvanced **I**ndustrial **S**cience and **T**echnology)

- Established in 2001 by reorganizing 16 institutes under METI
- Total income: 110 billion JPY
 - 90%: Government, 10%: Industry
- 2901 employees (as of July, 2022)
 - 2214 researchers
 - 687 administrative employees
 - + executives, visiting researchers, postdocs, technical staff
- 7 research departments



FREA (Fukushima Renewable Energy Institute, AIST)

- Established in Koriyama, Fukushima in 2014 for promoting
 - ▣ R&D of renewable energy internationally
 - ▣ Reconstruction of disaster area of 3.11



- Has over 200 researchers in 9 research teams



Energy Network



Hydrogen



Photovoltaic



Wind Power

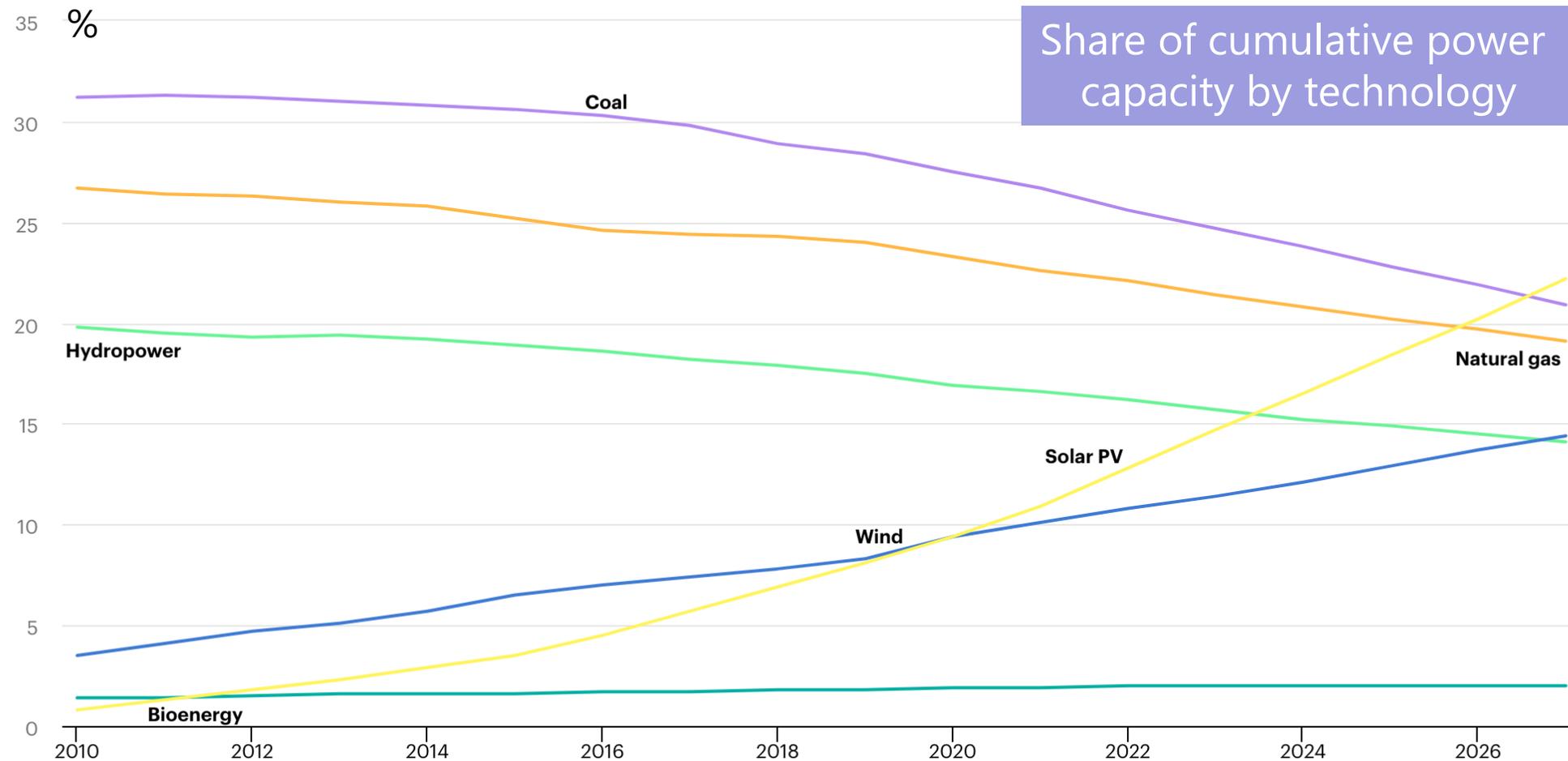


Geothermal



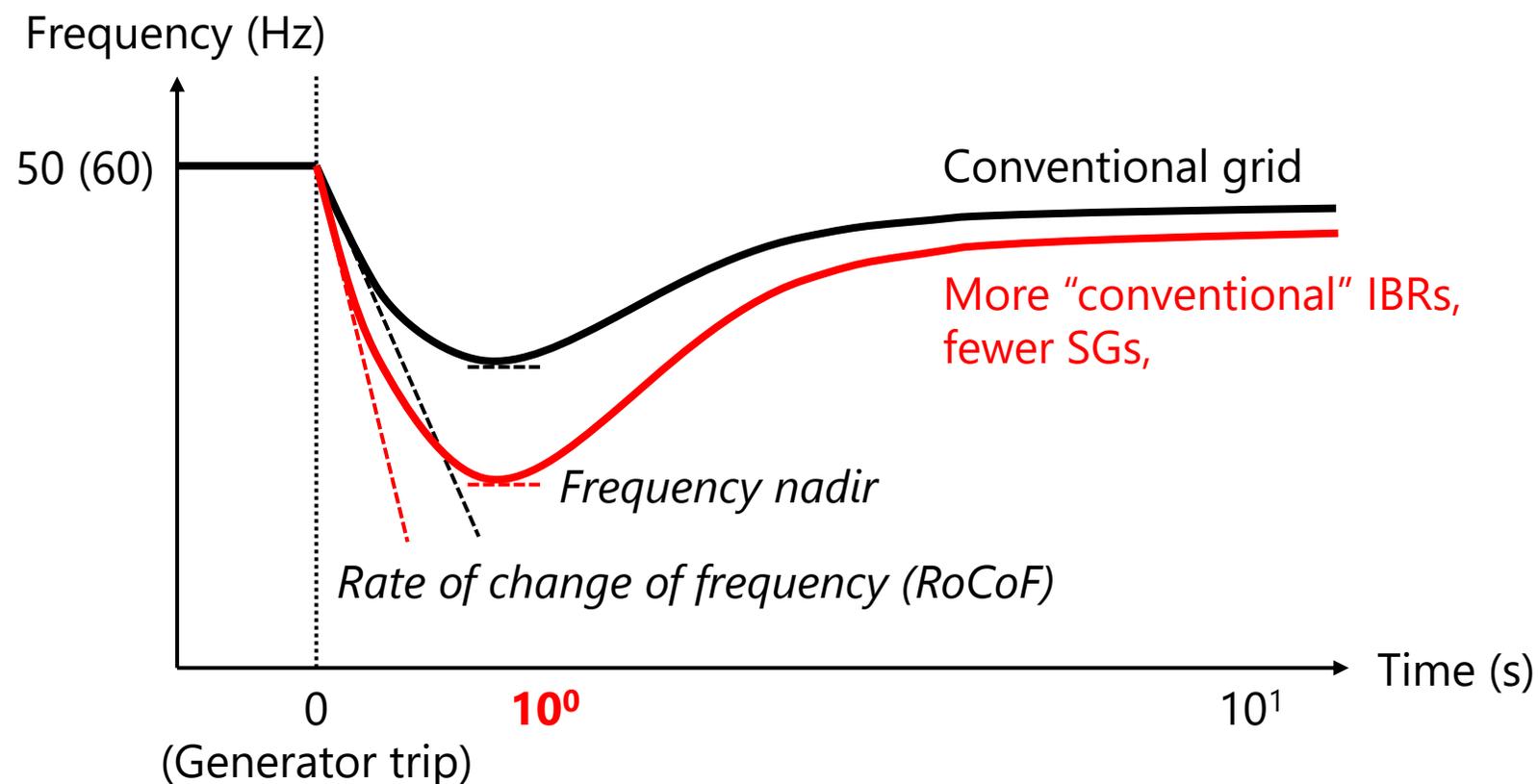
Shallow Geothermal

Inverter-based resources (IBRs) will increase, and synchronous generators (SGs) will decrease.



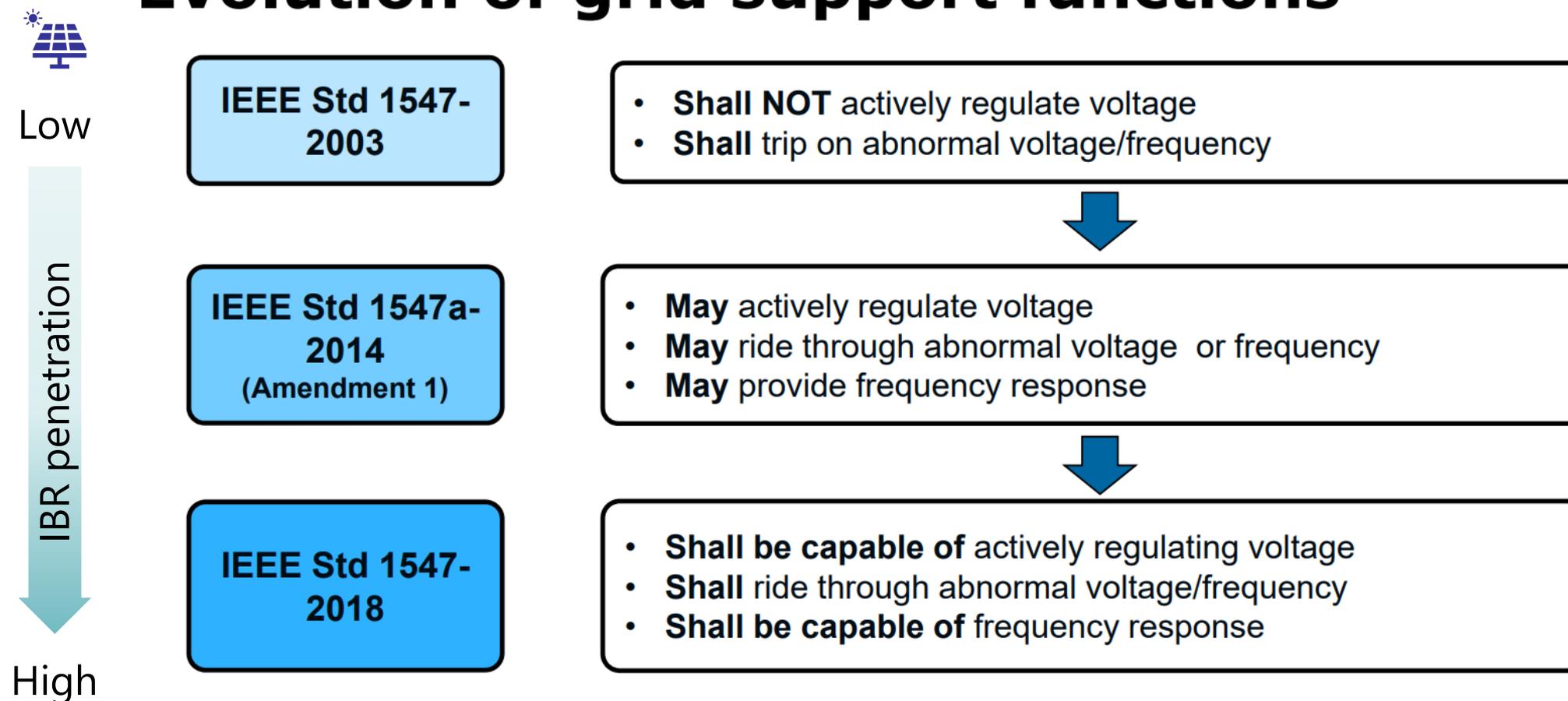
IBRs are expected to replace some of services provided by SGs

- Reducing the number of synchronous generators (SGs) decline grid frequency stability
- Frequency control including **inertial response** is required for inverter based-resources (IBRs)



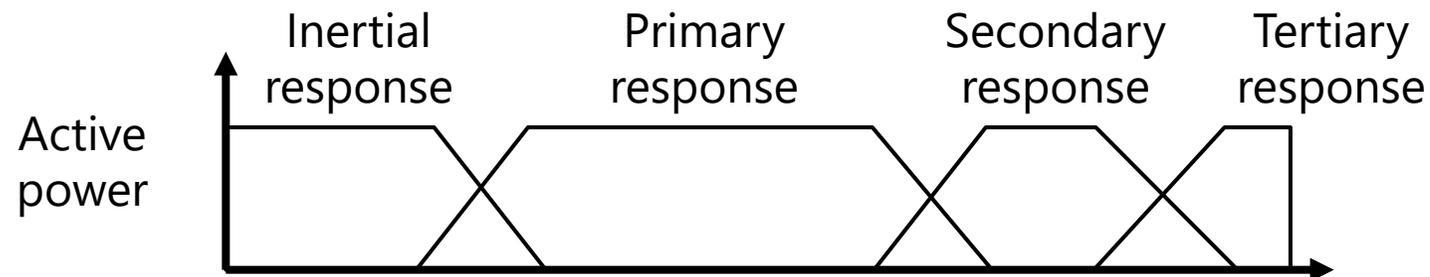
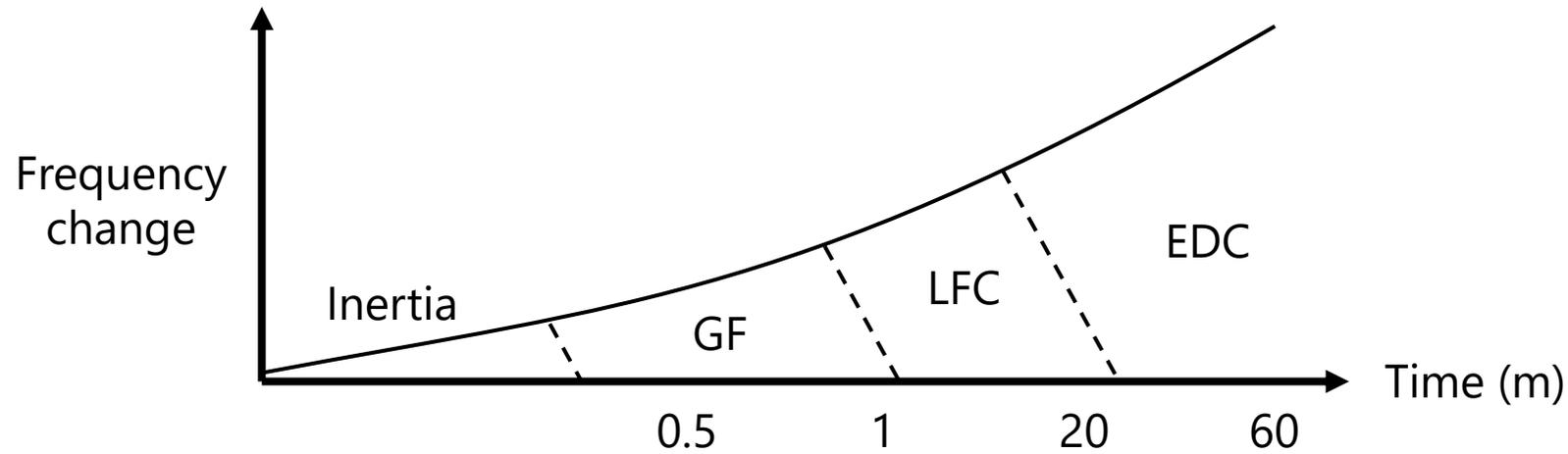
Changes in technical requirements due to increase in IBRs

Evolution of grid support functions



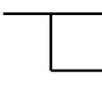
Source: NREL

Faster response is required for IBRs in low-inertia power systems



FFR, Frequency-watt control

Virtual inertia control

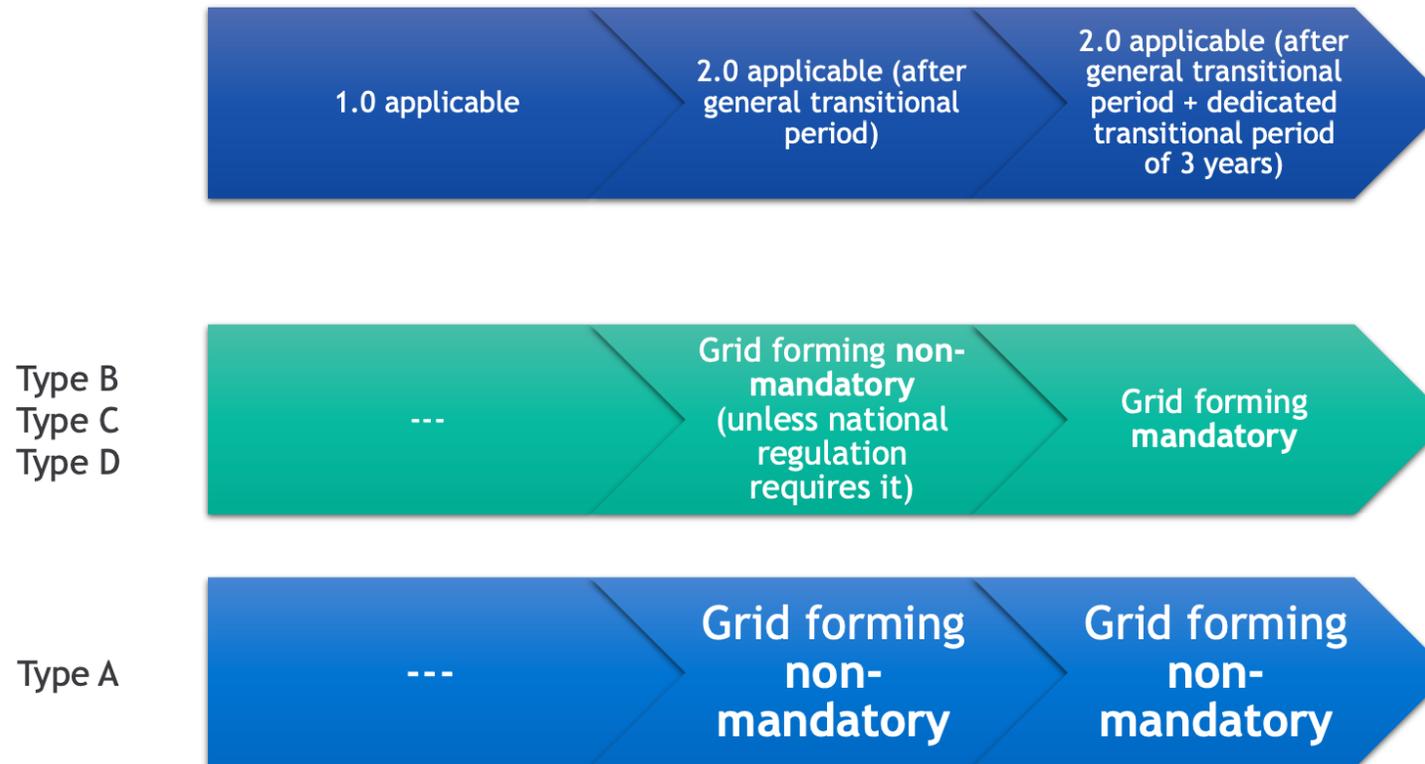

 Grid-following (GFL) inverter: acts as a current source

 Grid-forming (GFM) inverter: acts as a voltage source

Implementation of GFM capability is just around the corner

- NC RfG 2.0 with GFM requirement will enter in force in 2024 and will be reflected in national grid codes within three years

NC RfG 2.0 / Grid forming new Article

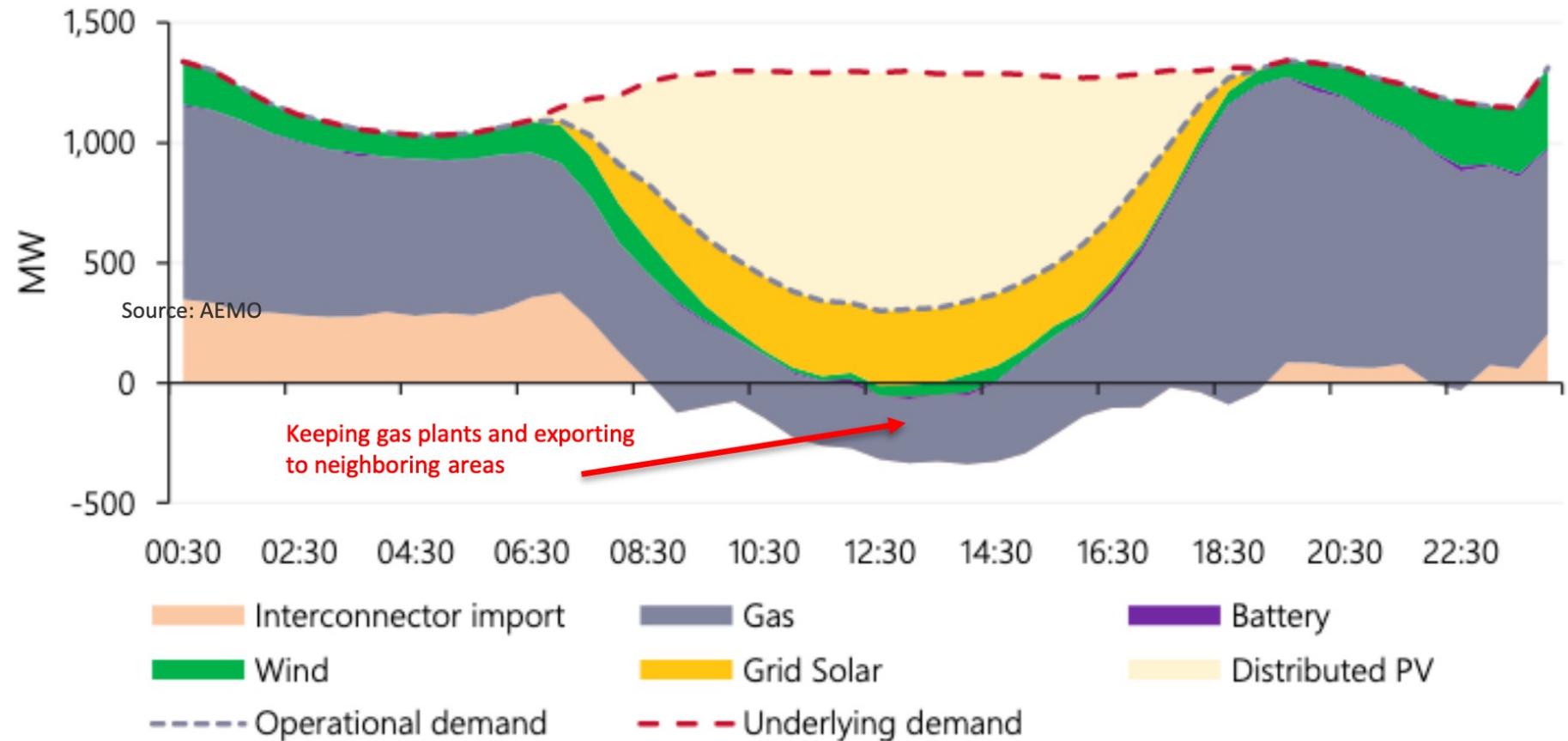


South Australia – Already at 100% IBR (but...)



SA solar (grid and distributed) meets 100% of South Australia's demand for the first time

South Australia operational demand by time of day – 11 October 2020



Tested five inverter prototypes with virtual inertia control

Grid-following inverter

Grid-forming inverter

GFL 1

GFL 2

GFM 0

GFM 1

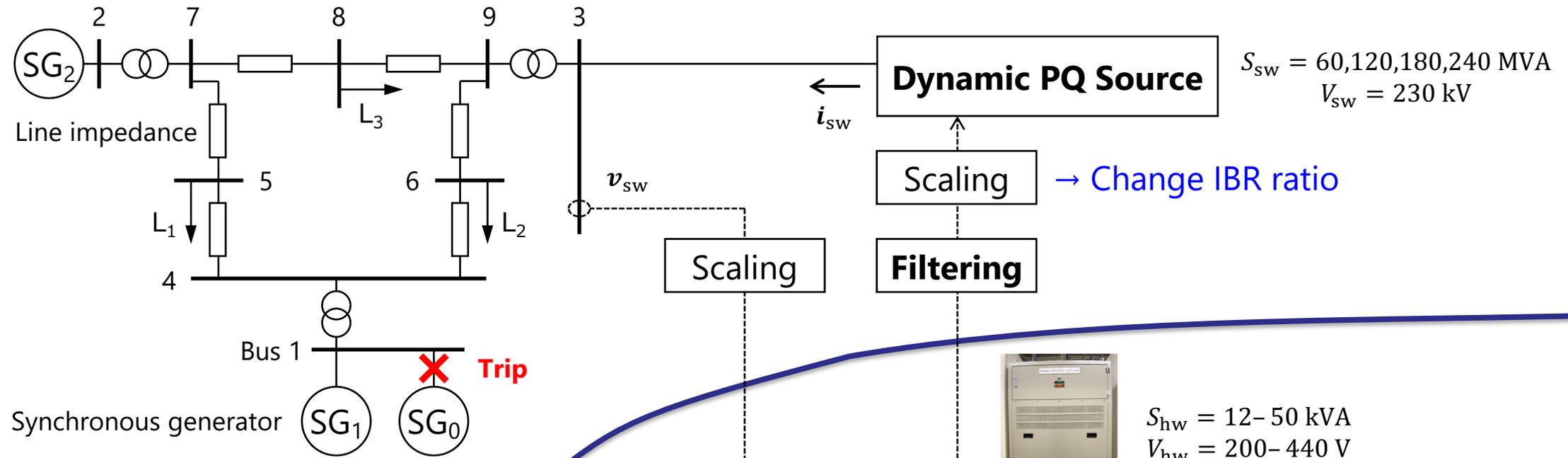
GFM 2

	Grid-following inverter		Grid-forming inverter		
	GFL 1	GFL 2	GFM 0	GFM 1	GFM 2
Control function	df/dt-P droop f-P droop	df/dt-P droop f-P droop	VSM Q-V droop	P-f droop Q-V droop	VSM Q-V droop
Rated capacity (kVA)	20	49.9	12	20	50
Rated AC voltage (V)	200	200	420	200	440



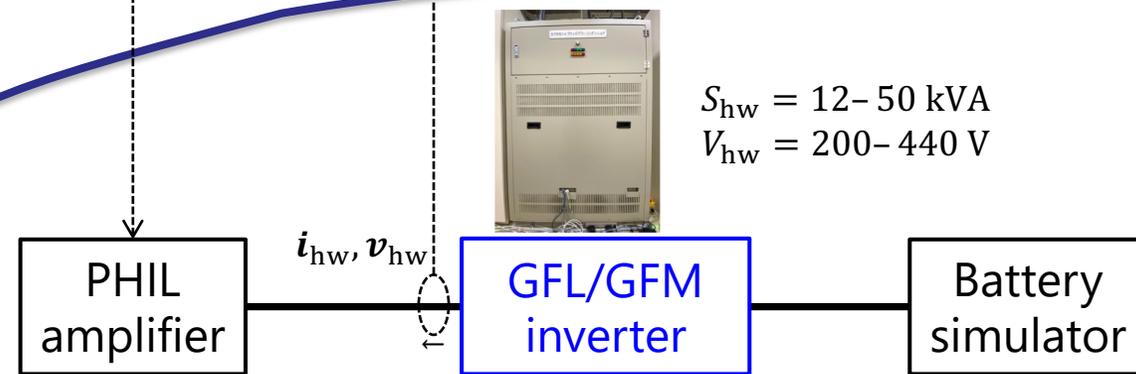
Test setup for GFL/GFM inverters using modified IEEE 9-bus system model

Modified IEEE 9-bus system model (300 MW)

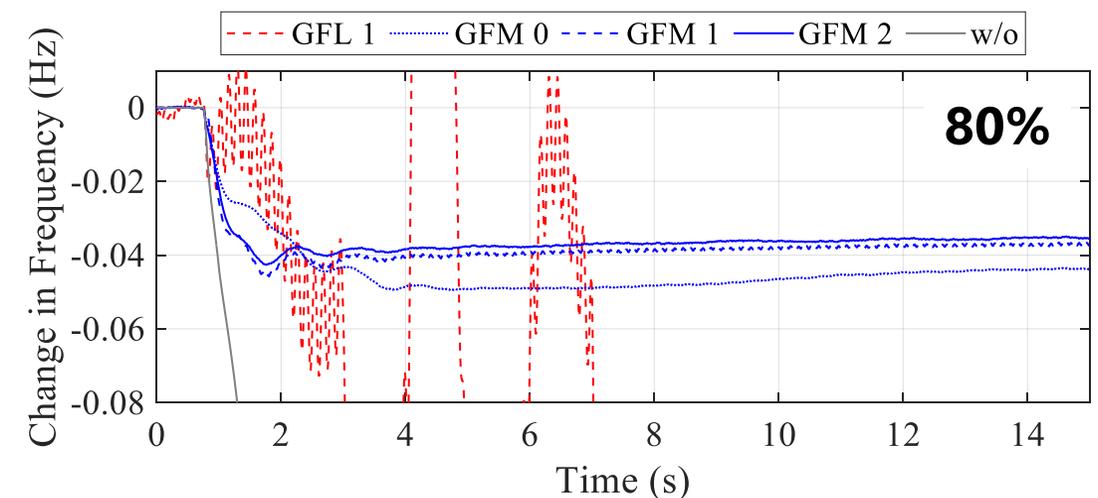
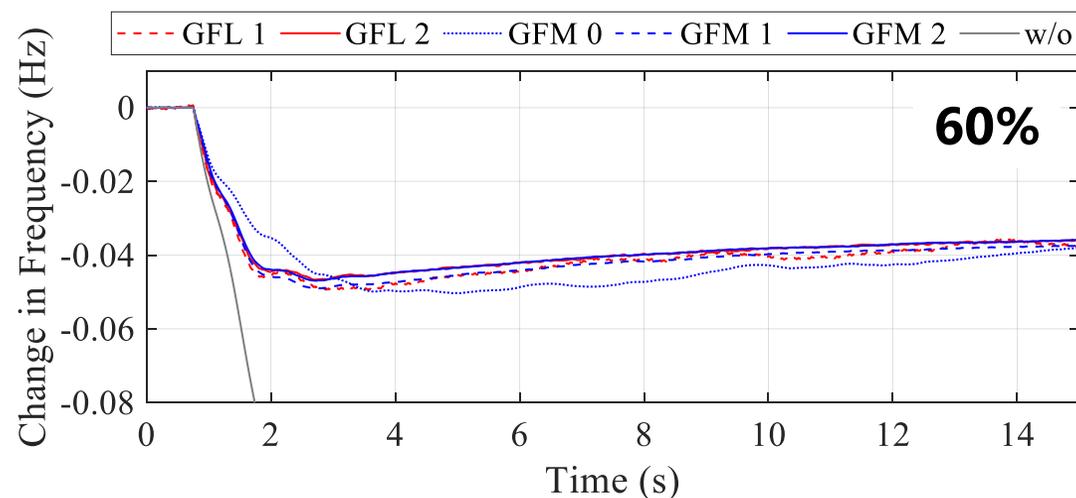
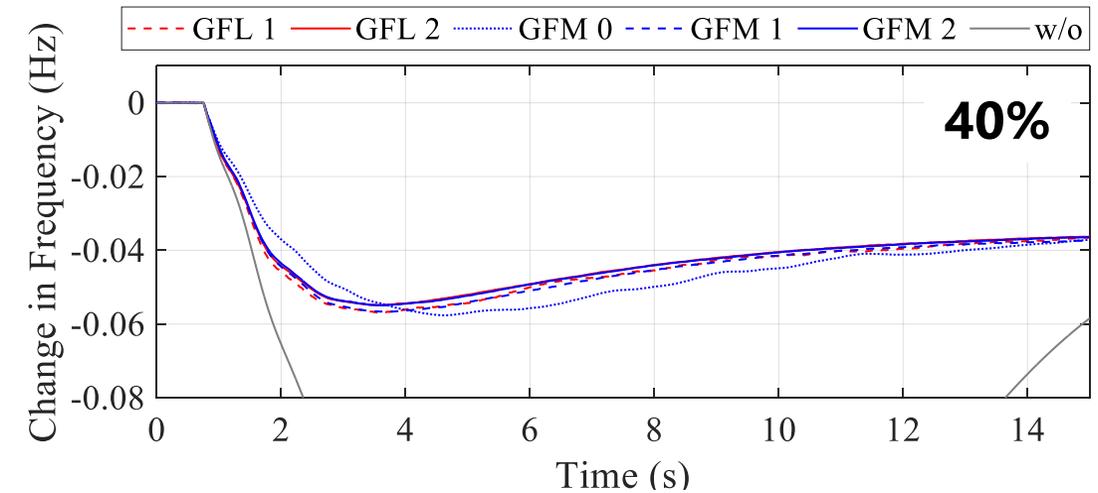
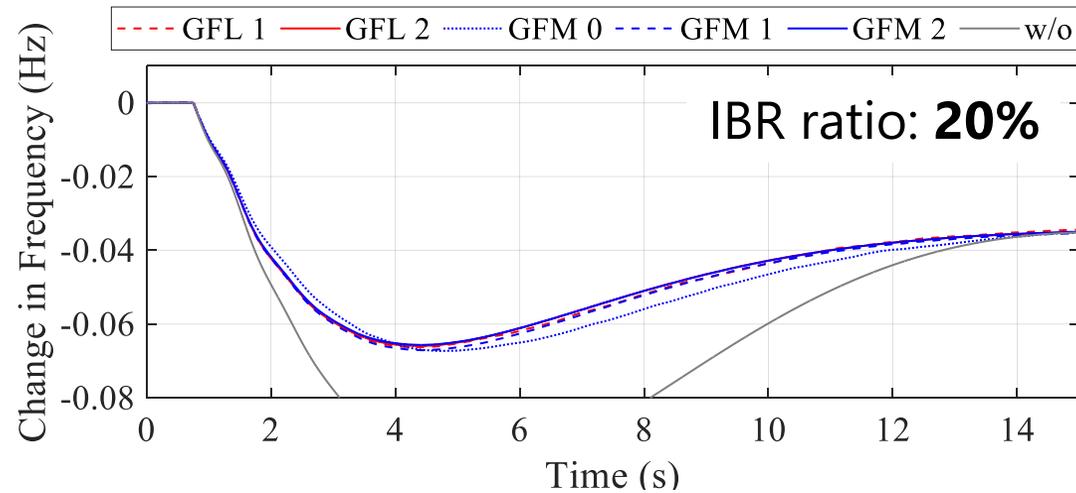


Digital real-time simulation (DRTS)

Hardware



As IBR ratio increased, frequency change increased for conventional IBR, decreased for GFL and GFM inverters. GFM inverters were stable at 80%.



Conducted existing conformance tests with changes in voltage magnitude, frequency, and phase angle. **GFL** inverters were mostly **conformance** in all tests. **GFM** inverters were **non-conformance** in most tests; **3 issues** were identified.

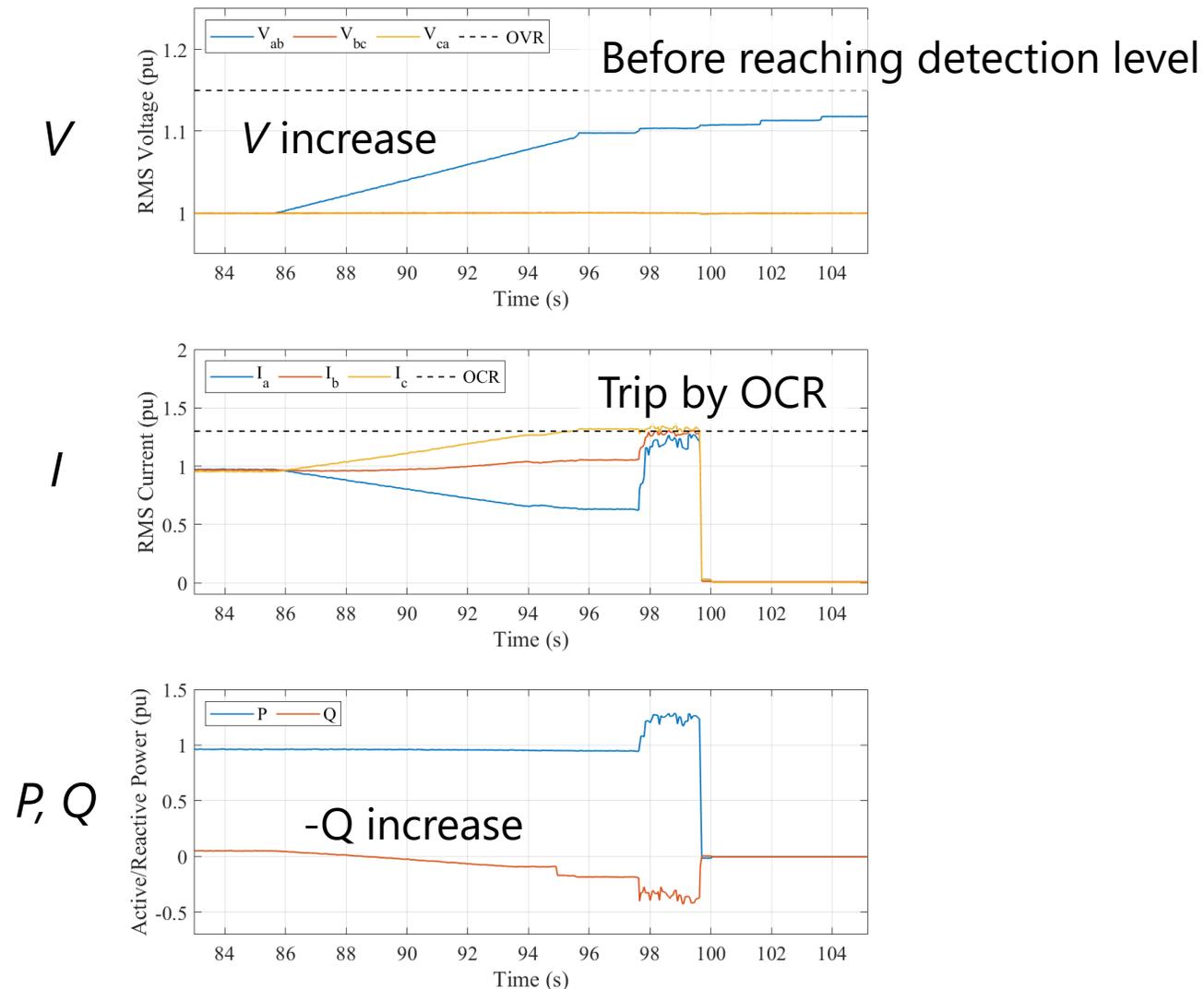
#	Test	GFL 1	GFL 2	GFM 0	GFM 1	GFM 2
1	Test for over/under-voltage trip	C*	C	N	N	N
2	Test for over/under-frequency trip	C*	C	N	N	N
3	Unintentional islanding test	C*	C*	-	N	C*
4	Test for voltage magnitude change within continuous operation region	C	C	N	C	C
5	Test for voltage phase angle change	C	C	C	N	N
6	Test for low/high-voltage ride-through	C*	C*	N	N	N
7	Test for low/high-frequency ride-through	C	C	N	N	C

C: Conformance; N: Non-conformance; -: Not conducted

* Conformance can be expected by minor changes to device configuration, control logic, etc.

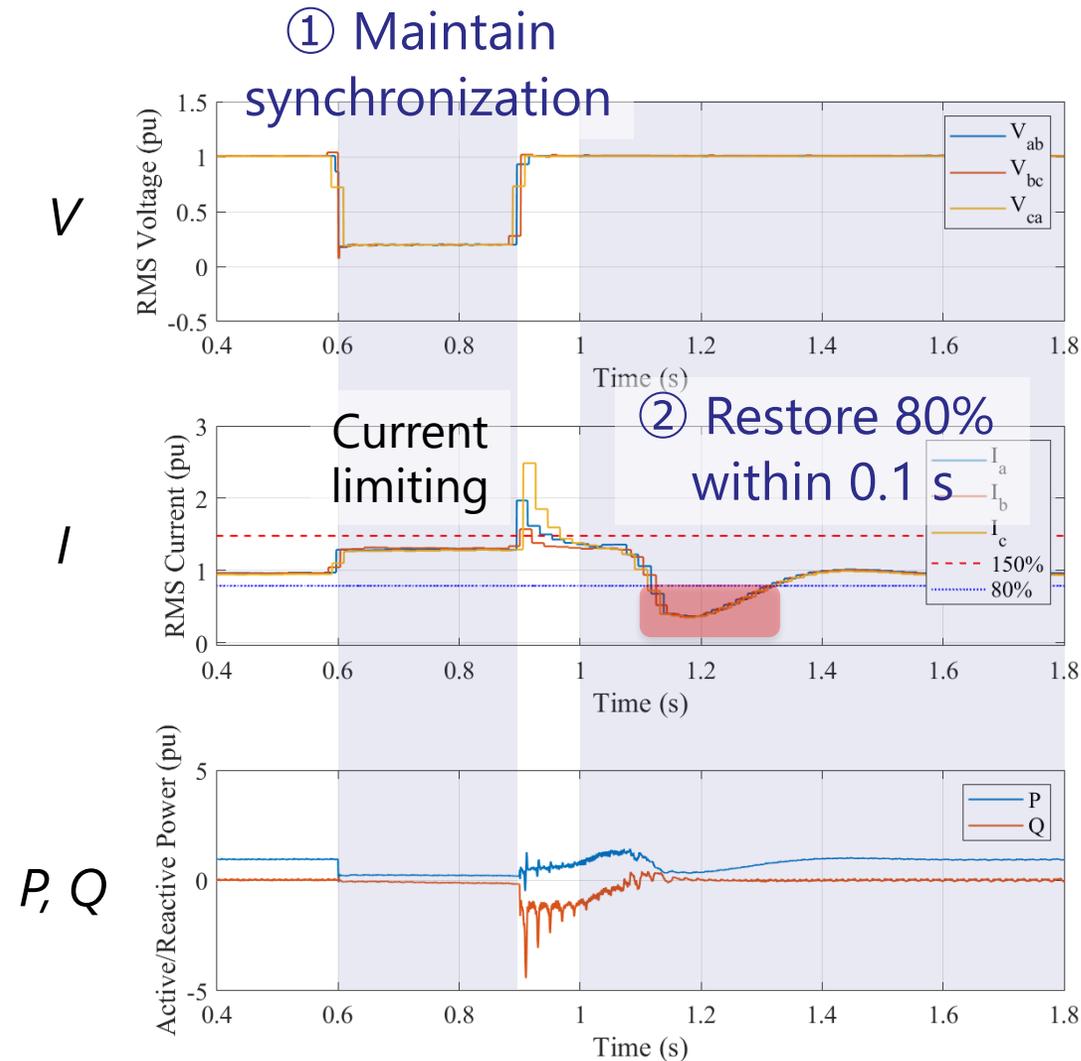
Issue 1: Unwanted tripping by OCR due to change in grid voltage

■ Test for over-voltage trip (GFM 0)



Issue 2: Active power swing after recovery from voltage sag

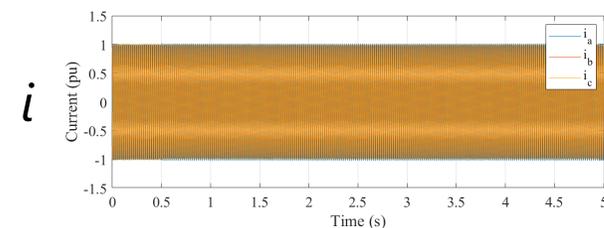
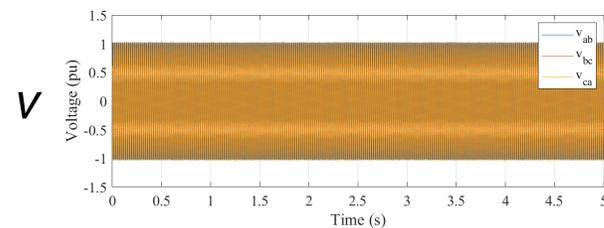
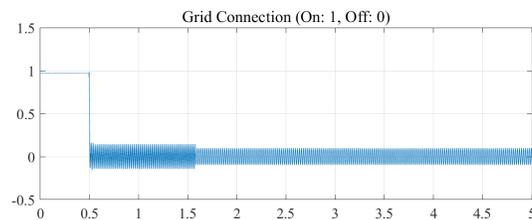
■ Low-voltage ride-through test (GFM 0)



Issue 3: Coexistence of grid stabilization capability and islanding detection

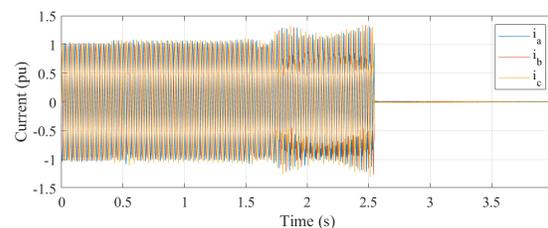
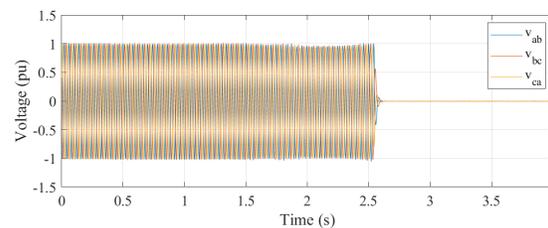
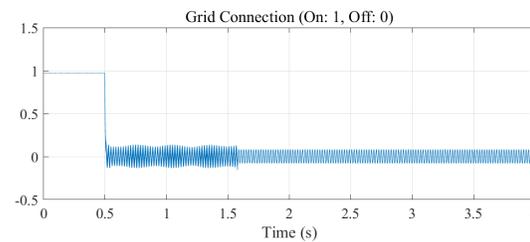
■ Unintentional islanding test

GFM 1



Continued to energize
→ **non-conformance**

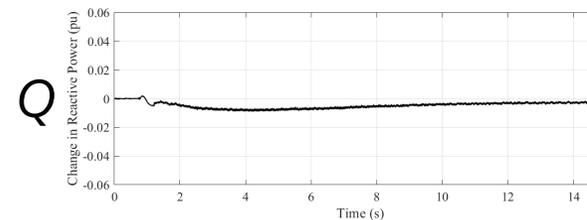
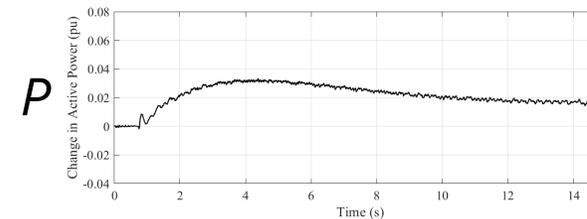
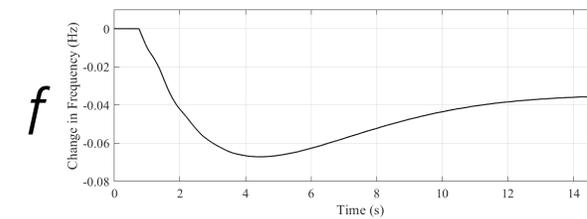
GFM 2



Ceased to energize
→ **conformance**

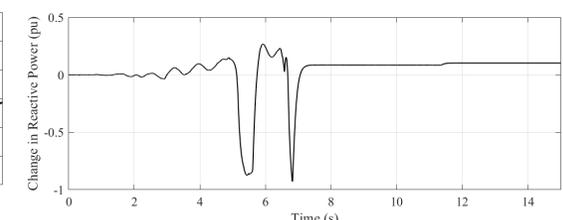
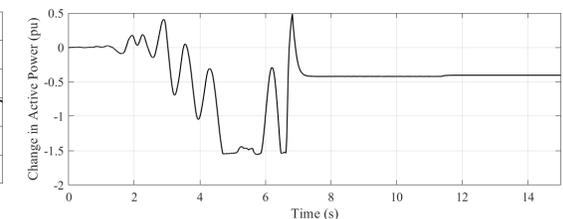
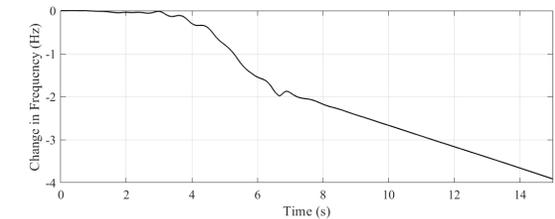
■ Frequency stability in PHIL testing

GFM 1



Stable

GFM 2



Unstable

Summary

- Tested five GFL and GFM inverters from different manufacturers
- PHIL testing with IEEE 9-bus system model
 - As the IBR ratio increased, frequency change increased for conventional IBR, decreased for GFL and GFM inverters
 - GFM inverters were stable at 80%
- Japan's existing conformance testing
 - GFL Inverters were mostly conformance in all tests
 - GFM Inverters were non-conformance in most tests
 - Issue 1: Unwanted tripping by OCR due to a change in grid voltage
 - Issue 2: Active power swing after recovery from voltage sag
 - Issue 3: Coexistence of grid stabilization capability and islanding detection
- Working on a subsequent national R&D project for practical application of GFM inverter

Appendix

Related Works

- H. Kikusato et al., "Performance Evaluation of Grid-Following and Grid-Forming Inverters on Frequency Stability in Low-Inertia Power Systems by Power Hardware-in-the-Loop Testing," Energy Reports 2023, 9 (supplement 1), 381–392.
- H. Kikusato et al., "Performance Analysis of Grid-Forming Inverters in Existing Conformance Testing," Energy Reports 2022, 8 (supplement 15), 73–83.
- H. Kikusato et al., "Verification of Power Hardware-in-the-Loop Environment for Testing Grid-Forming Inverter," Energy Reports 2023, 9 (supplement 3), 303–311.
- H. Kikusato et al., "Power Hardware-in-the-Loop Testing for Multiple Inverters with Virtual Inertia Controls," Energy Report 2023, 9 (supplement 10), 458–466.
- D. Orihara et al., "Contribution of Voltage Support Function to Virtual Inertia Control Performance of Inverter-Based Resource in Frequency Stability," Energies 2021, 14, 4220.
- D. Orihara et al., "Internal Induced Voltage Modification for Current Limitation in Virtual Synchronous Machine," Energies 2022, 15, 901.
- J. Hashimoto et al., "Development of df/dt Function in Inverters for Synthetic Inertia," Energy Reports 2023, 9 (supplement 1), 363–371.
- J. Hashimoto et al., "Developing a Synthetic Inertia Function for Smart Inverters and Studying its Interaction with Other Functions with CHIL Testing," Energy Reports 2023, 9 (supplement 1), 435–443.
- T. Takamatsu et al., "Simulation Analysis of Issues with Grid Disturbance for a Photovoltaic Powered Virtual Synchronous Machine," Energies 2022, 15, 5921.
- H. Hamada et al., "Challenges for a Reduced Inertia Power System Due to the Large-Scale," Global Energy Interconnection 2022, 5(3), 266–273.

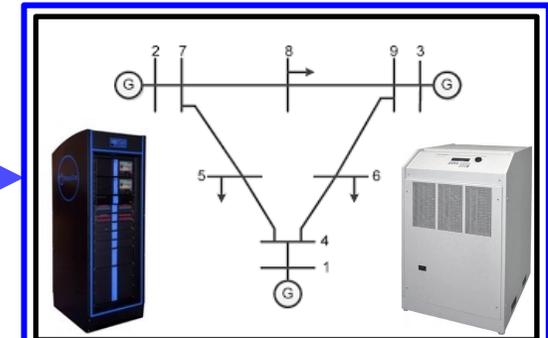
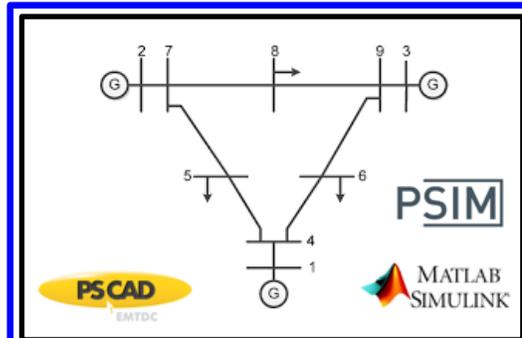
PHIL Simulation is a Flexible and Reliable Testing Method

Simulation

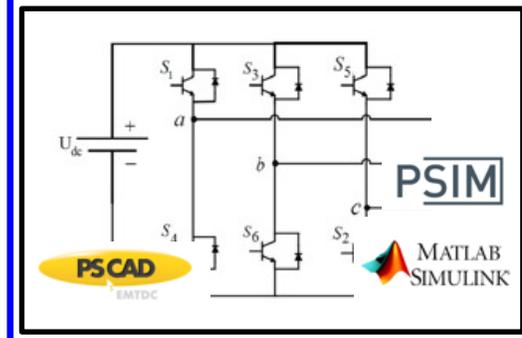
Demonstration

Power hardware-in-the-loop (PHIL) simulation

Grid



GFMI



Flexibility (Grid)

High

Low

High

Fidelity (GFMI)

Low

High

High

Advanced Control of GFL and GFM inverters

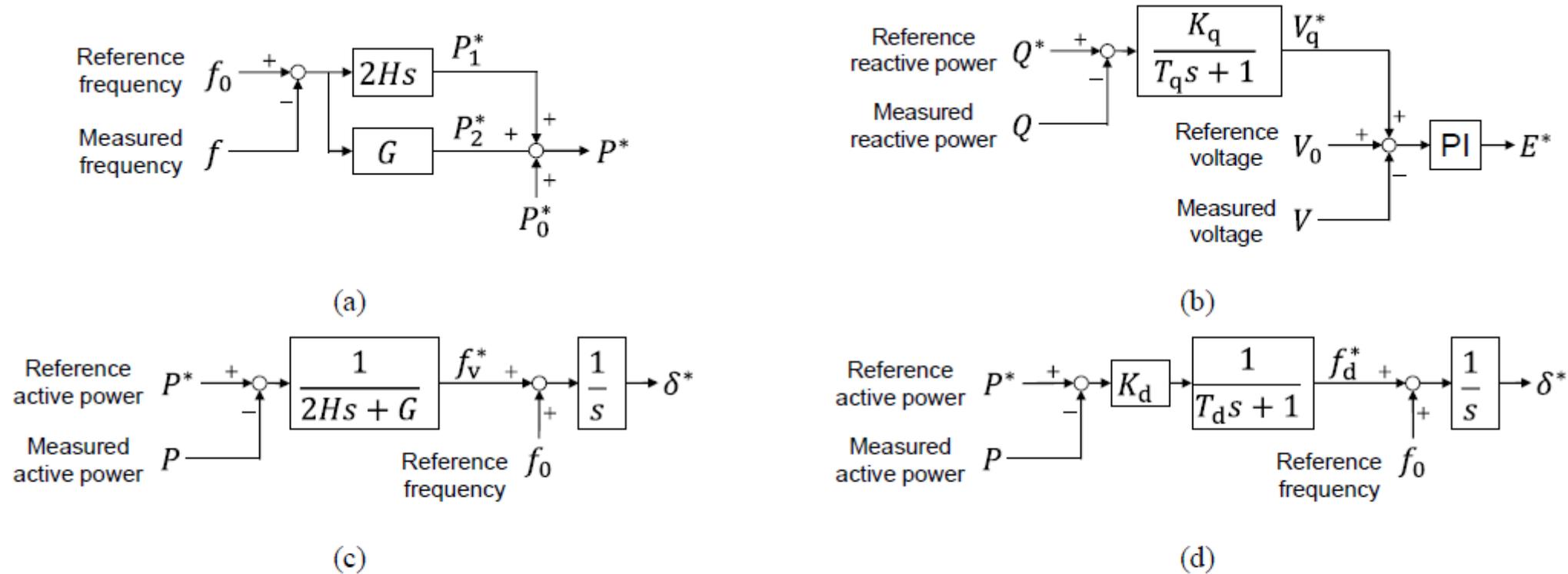


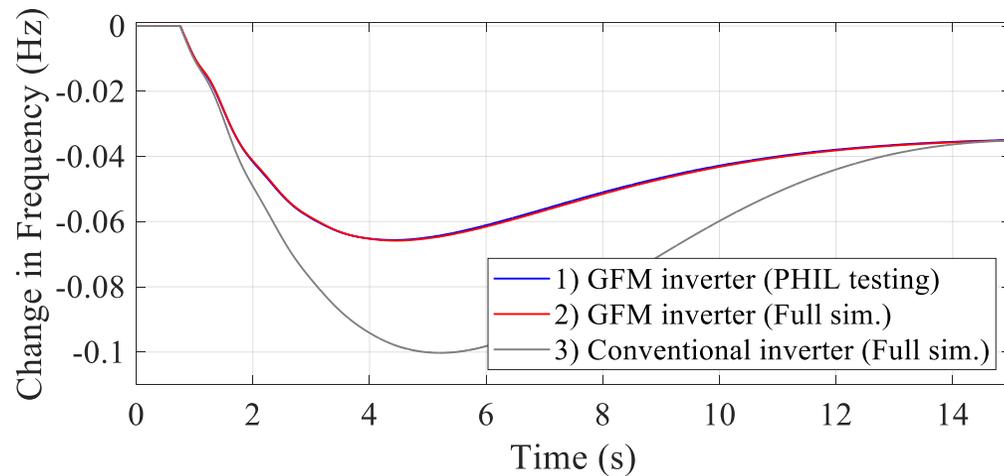
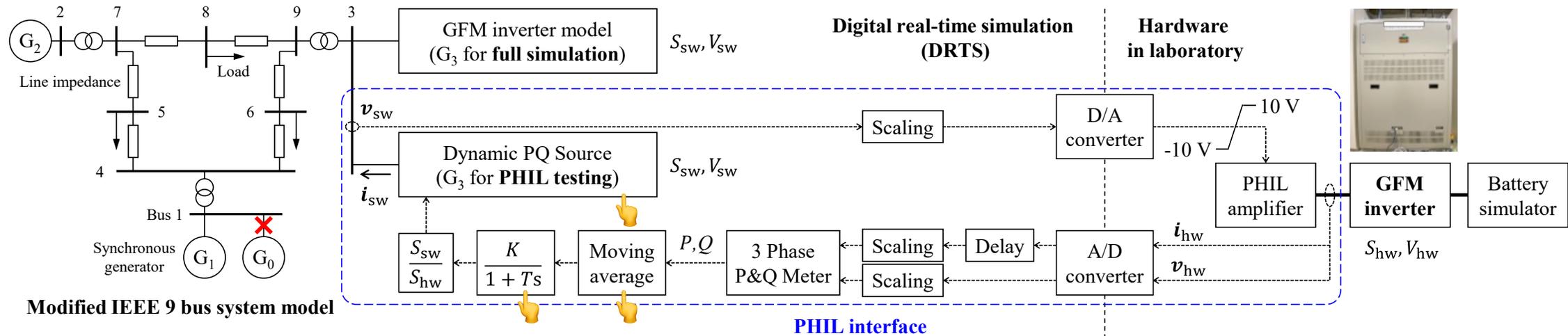
Fig. 2. Generalized control block diagrams of (a) the frequency control implemented in GFL 1 and GFL 2; (b) the voltage magnitude control implemented in GFM 0, GFM 1, and GFM 2; the voltage phase angle control implemented in (c) GFM 0, GFM 2; and (d) GFM 1.

Specifications of inverters

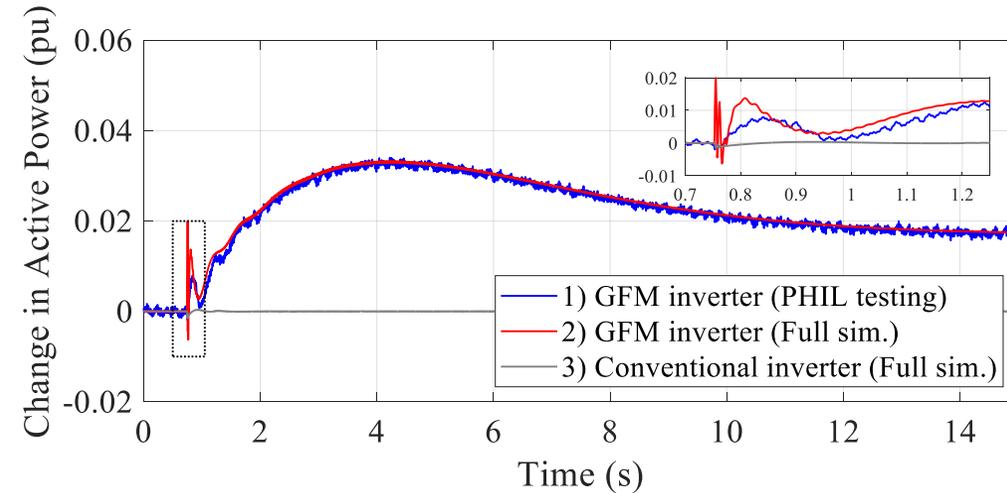
Table 2. Specifications of inverter prototypes.

Name and inverter types	GFL 1	GFL 2	GFM 0	GFM 1	GFM 2
Rated capacity	20 kVA	49.9 kVA	12 kVA	20 kVA	50 kVA
Advanced control functions	df/dt-P droop, f-P droop	df/dt-P droop, f-P droop	VSM, Q-V droop	P-f droop, Q-V droop	VSM, Q-V droop
IDM (reactive method; active method)	Voltage phase angle jump detection; Frequency feedback method with step reactive power injection	RoCoF change detection; Frequency shift method	Unimplemented	Voltage phase angle jump detection; Frequency feedback method with step reactive power injection	Voltage phase angle jump detection; Frequency feedback method with step reactive power injection
Current limiting function	w/	w/	w/	w/o	w/
Prototype number	Prototype 1	Prototype 2	Prototype 3	Prototype 1	Prototype 4

PHIL Testing Can be Conducted Stably in Most Cases with Adequate Accuracy

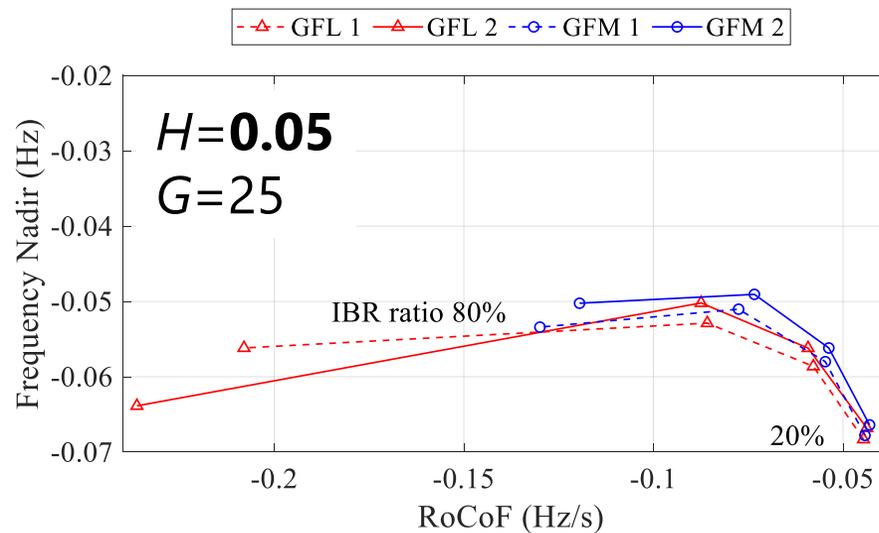
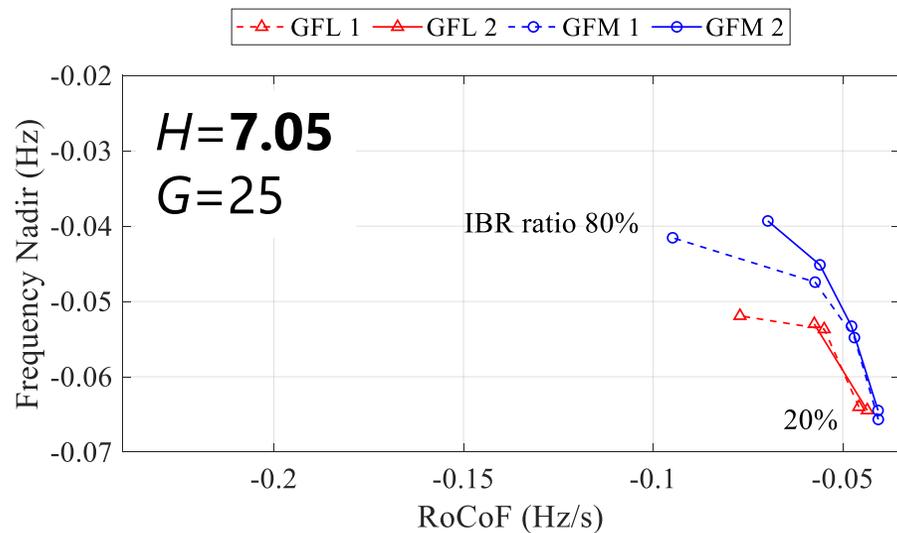
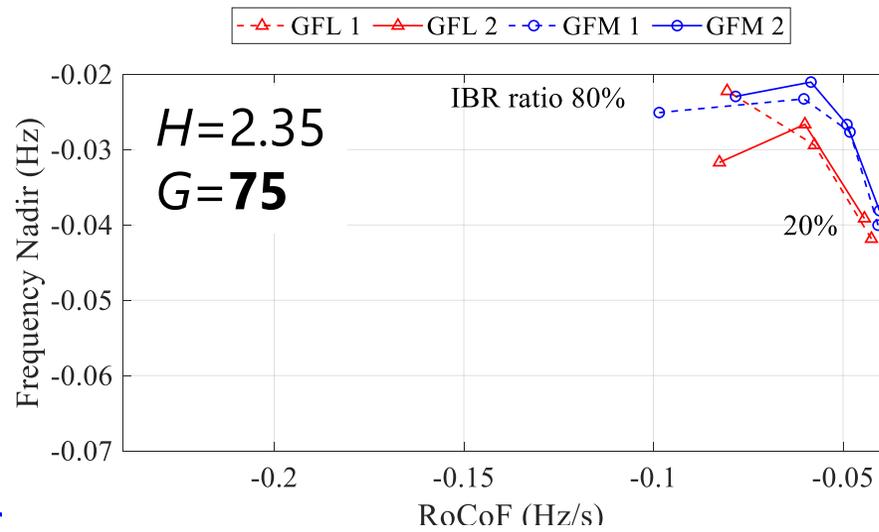
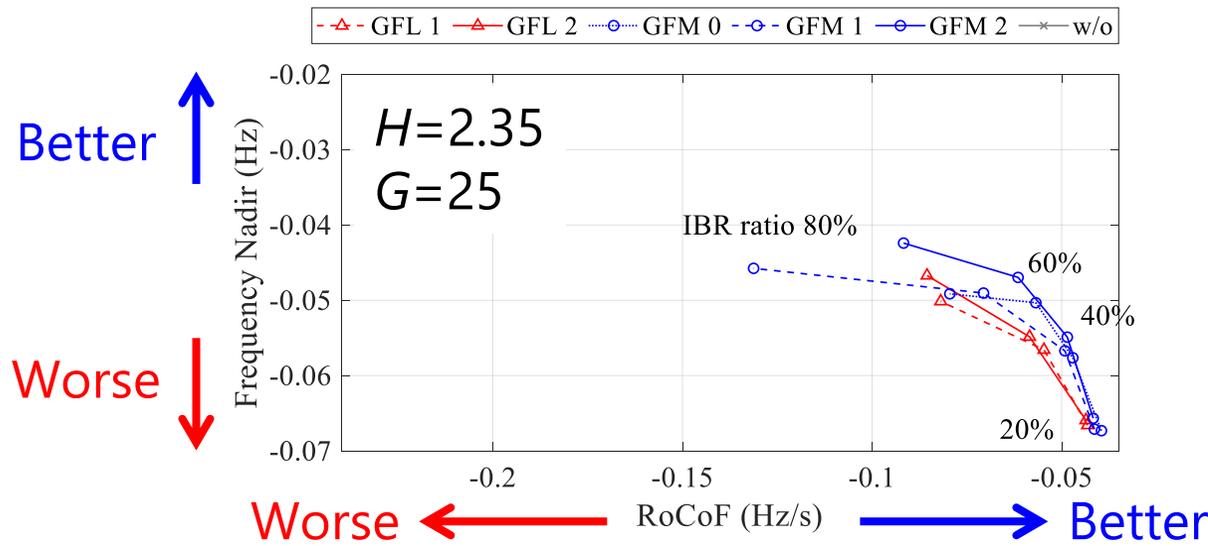


Frequency

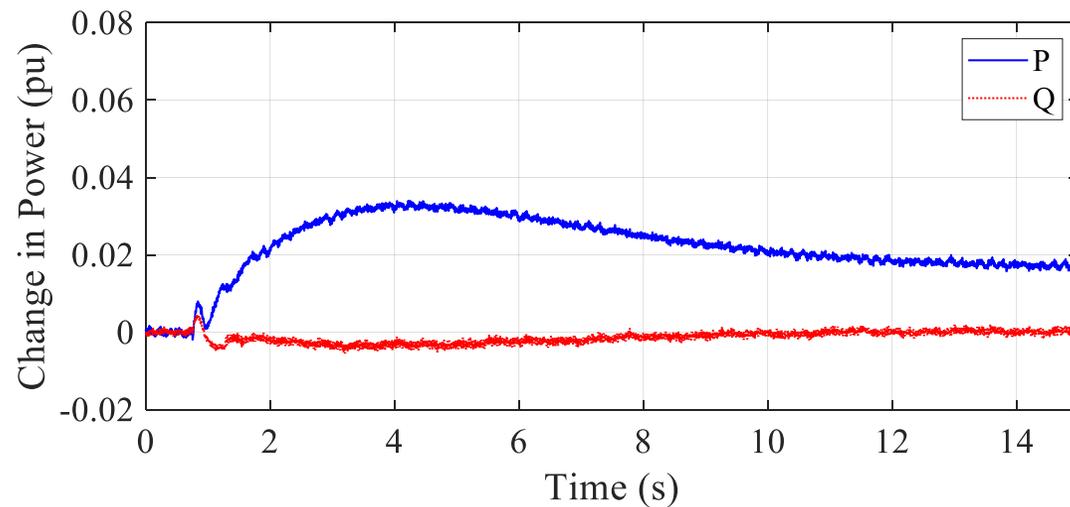
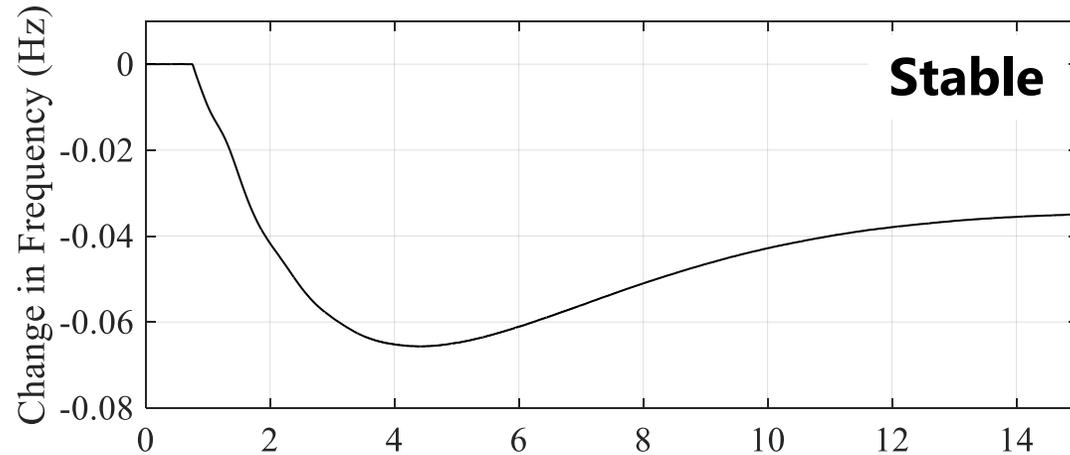


Active power

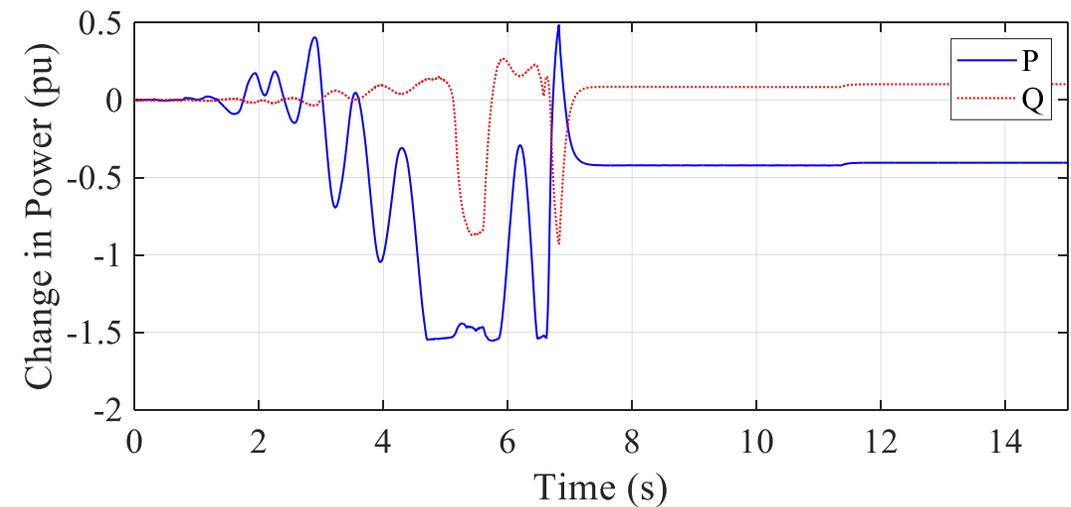
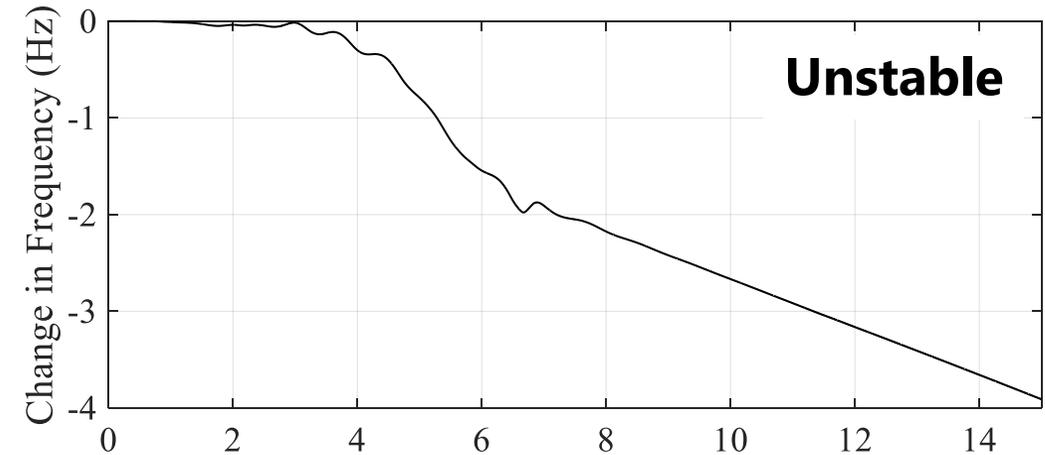
Inertia Constant "H" Affects RoCoF; Governor Gain "G" Affects Frequency Nadir (and RoCoF)



Interference Occurs between Islanding Detection and Frequency Stabilization Capability in GFM Inverter

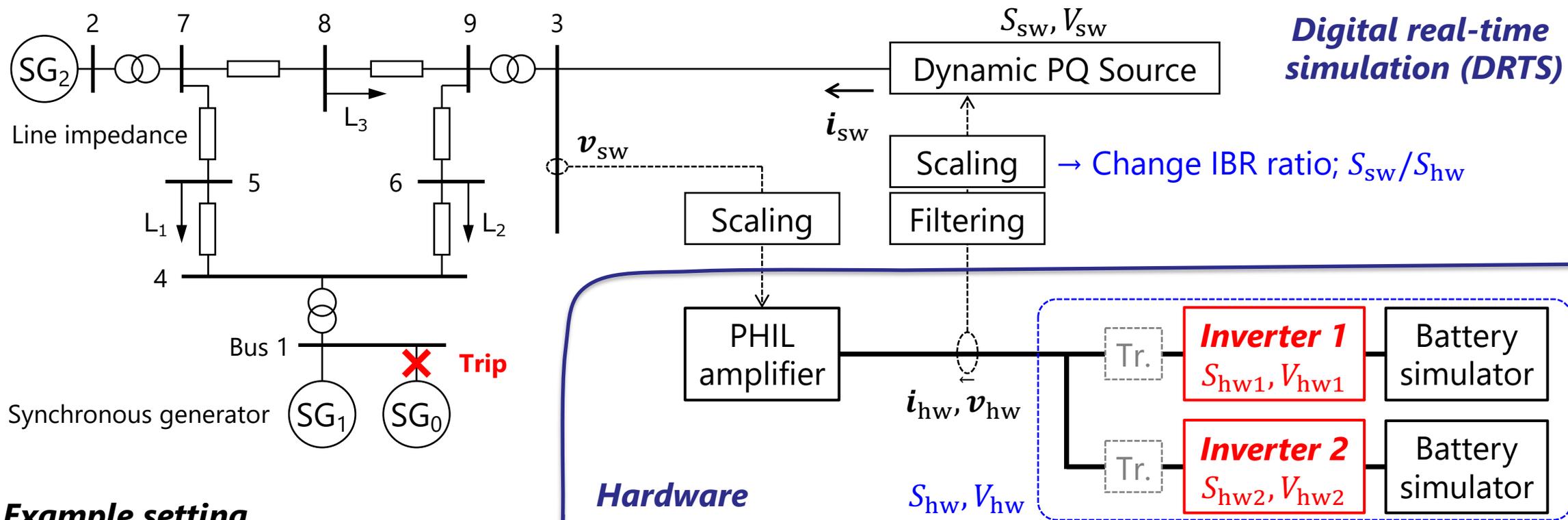


Disable islanding detection



Enable islanding detection

Configuration of PHIL testing for multiple inverters



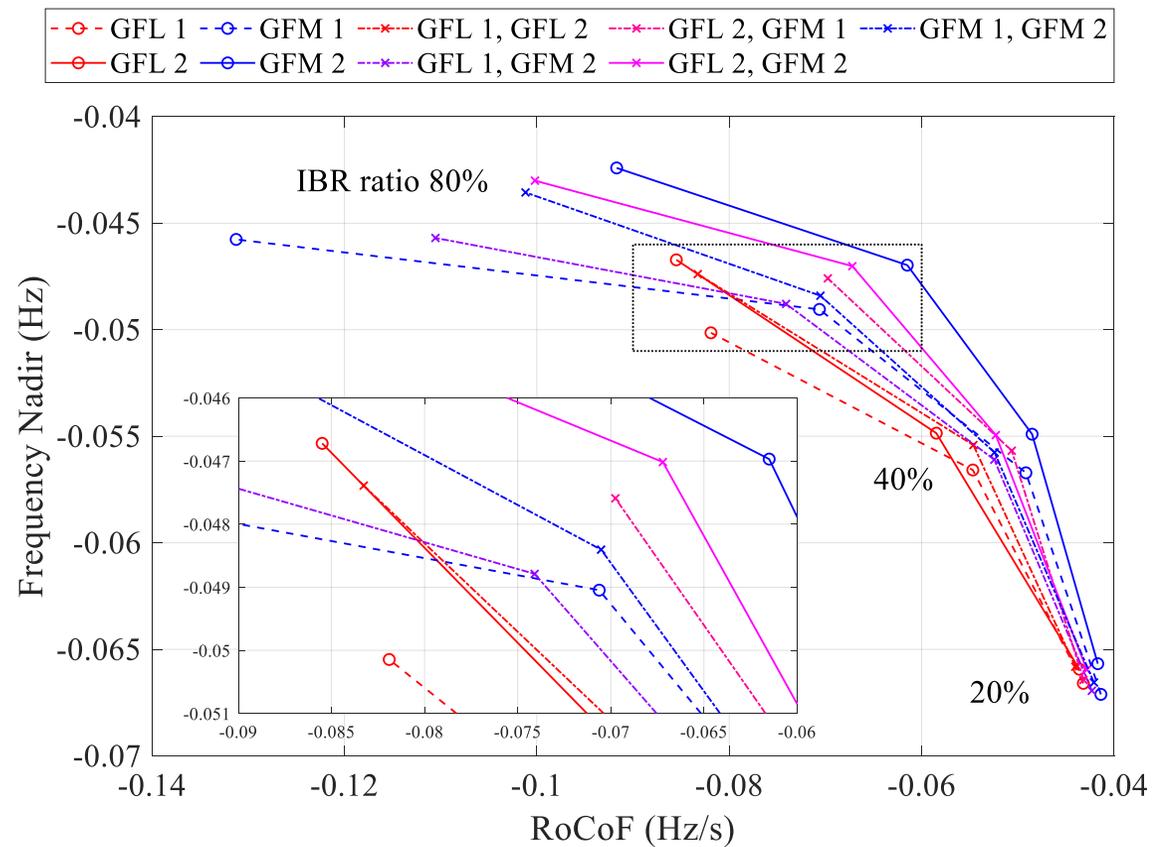
Digital real-time simulation (DRTS)

Hardware

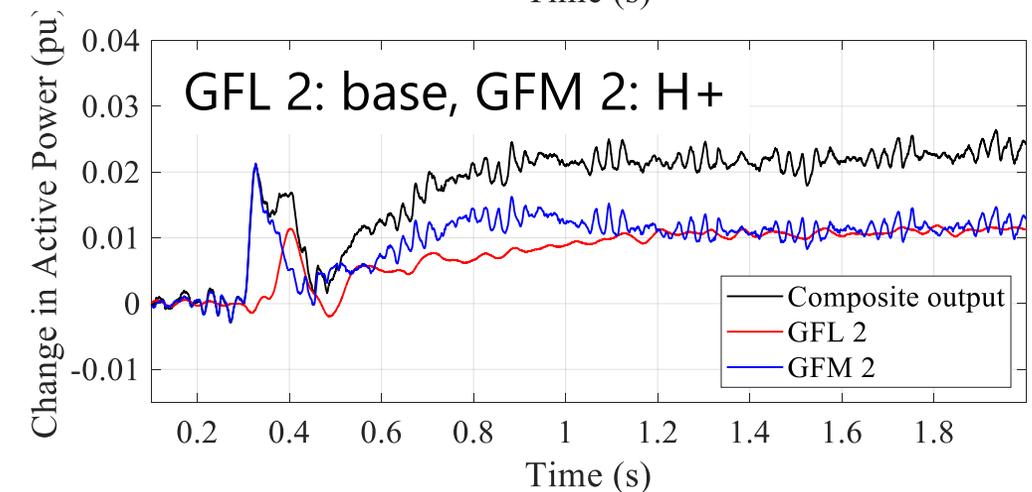
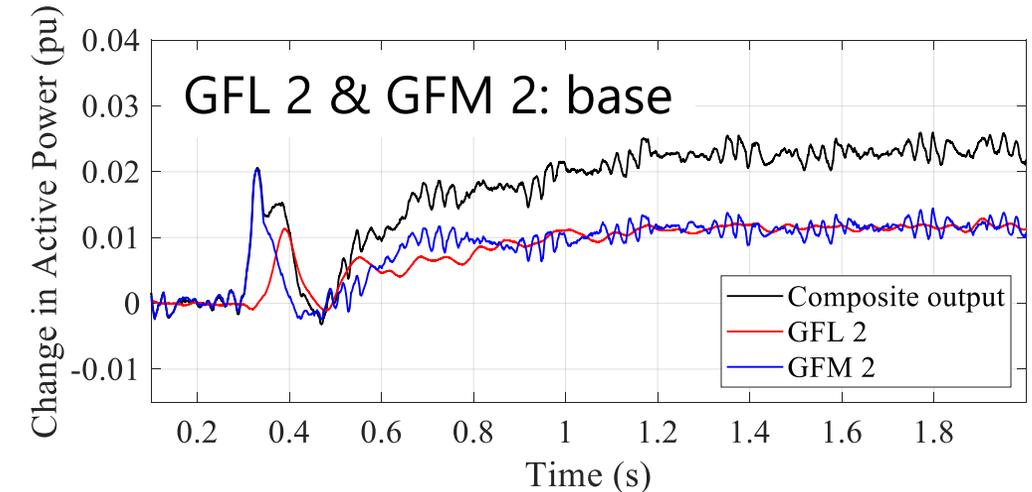
Example setting

Inverter 1	$S_{hw1} = 20 \text{ kVA} \Rightarrow S'_{hw1} = 20 \text{ kVA}$	$V_{hw1} = 200 \text{ V} \Rightarrow \text{use Tr.}$	$H'_1 = \frac{S'_{hw1}}{S_{hw1}} \times H_1, G'_1 = \frac{S'_{hw1}}{S_{hw1}} \times G_1$
Inverter 2	$S_{hw2} = 50 \text{ kVA} \Rightarrow S'_{hw2} = 20 \text{ kVA}$	$V_{hw2} = 440 \text{ V}$	$H'_2 = \frac{S'_{hw2}}{S_{hw2}} \times H_2, G'_2 = \frac{S'_{hw2}}{S_{hw2}} \times G_2$
Total setting	$S_{hw} = S'_{hw1} + S'_{hw2} = 40 \text{ kVA}$	$V_{hw} = 440 \text{ V}$	-

No inverter combination caused interference that significantly worsened the grid frequency stability. Combined inverters' performance was intermediate between the performance of each inverter alone.



RoCoF and frequency nadir



Active power

8 GFM batteries with total capacity of 2.0 GW/4.2 GWh

